

UTILITY PATENT APPLICATION TRANSMITTAL

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(Only for new nonprovisional applications under 37 CFR 1.53(b))

Docket No.
SAR 13076

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Washington, D.C. 20231

EI418658788US

Transmitted herewith for filing under 35 U.S.C. 111(a) and 37 C.F.R. 1.53(b) is a new utility patent application for
invention entitled:

METHOD AND APPARATUS FOR GENERIC SCALABLE SHAPE CODING

and invented by:

SHIPENG LI

If a **CONTINUATION APPLICATION**, check appropriate box and supply the requisite information:

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Enclosed are:

Application Elements

1. ☒ Filing fee as calculated and transmitted as described below
2. ☒ Specification having 47 pages and including the following:
 - a. ☒ Descriptive Title of the Invention
 - b. ☒ Cross References to Related Applications (if applicable)
 - c. ☐ Statement Regarding Federally-sponsored Research/Development (if applicable)
 - d. ☐ Reference to Microfiche Appendix (if applicable)
 - e. ☒ Background of the Invention
 - f. ☒ Brief Summary of the Invention
 - g. ☒ Brief Description of the Drawings (if drawings filed)
 - h. ☒ Detailed Description
 - i. ☒ Claim(s) as Classified Below
 - j. ☒ Abstract of the Disclosure

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Application Elements (Continued)

3. ☒ Drawing(s) *(when necessary as prescribed by 35 USC 113)*
- a. ☒ Formal Number of Sheets 11
- b. ☐ Informal Number of Sheets _____
4. ☒ Oath or Declaration
- a. ☒ Newly executed *(original or copy)* ☐ Unexecuted
- b. ☐ Copy from a prior application (37 CFR 1.63(d)) *(for continuation/divisional application only)*
- c. ☒ With Power of Attorney ☐ Without Power of Attorney
- d. ☐ DELETION OF INVENTOR(S)
Signed statement attached deleting inventor(s) named in the prior application,
see 37 C.F.R. 1.63(d)(2) and 1.33(b).
5. ☐ Incorporation By Reference *(usable if Box 4b is checked)*
The entire disclosure of the prior application, from which a copy of the oath or declaration is supplied under
Box 4b, is considered as being part of the disclosure of the accompanying application and is hereby
incorporated by reference therein.
6. ☐ Computer Program in Microfiche *(Appendix)*
7. ☐ Nucleotide and/or Amino Acid Sequence Submission *(if applicable, all must be included)*
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- c. ☐ Statement Verifying Identical Paper and Computer Readable Copy

Accompanying Application Parts

8. ☒ Assignment Papers *(cover sheet & document(s))*
9. ☐ 37 CFR 3.73(B) Statement *(when there is an assignee)*
10. ☐ English Translation Document *(if applicable)*
11. ☐ Information Disclosure Statement/PTO-1449 ☐ Copies of IDS Citations
12. ☐ Preliminary Amendment
13. ☒ Acknowledgment postcard
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15. ☐ Certified Copy of Priority Document(s) (if foreign priority is claimed)

16. ☐ Additional Enclosures (please identify below):

Fee Calculation and Transmittal

CLAIMS AS FILED

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Total Claims	30	- 20 =	10	x \$18.00	\$180.00
Indep. Claims	3	- 3 =	0	x \$78.00	\$0.00
Multiple Dependent Claims (check if applicable) <input type="checkbox"/>					\$0.00
BASIC FEE					\$760.00
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Dated: 14 MAY 1999

CC:

METHOD AND APPARATUS FOR GENERIC SCALABLE SHAPE CODING

This application claims the benefit of U.S. Provisional Application
5 No. 60/090,815 filed June 26, 1998 and U.S. Provisional Application No.
60/103,012 filed October 5, 1998, which are herein incorporated by
reference.

The invention relates to an apparatus and a concomitant method for
10 shape or object mask coding. More particularly, the invention relates to a
method for increasing the efficiency of scalable shape coding by
correlating the coding of the mask of the object between different scales.

BACKGROUND OF THE INVENTION

15 Shape or object mask encoding (also known as object-oriented image
and video coding) has gained acceptance and is presently being promoted
to various multimedia standards, e.g., the MPEG-4 (Moving Picture
Experts Group) international standard. However, unlike traditional
frame encoding methods, each frame or picture is considered as
20 consisting of one or more flexible objects (objects having arbitrary shapes),
that may undergo changes such as translations, rotations, scaling,
brightness and color variations and the like. Using shape or object mask
encoding, functionalities are not only provided at the frame level, but also
at the object level.

25 One functionality is scalability, i.e., providing an image at different
spatial resolutions. In general, shape encoding starts by segmenting an
image frame into a plurality of objects or video object planes (VOPs), e.g., a
speaker in an image is one object and the background is a second object.
The resulting "shape information" can be represented as a "binary mask".
30 A mask can be broadly defined as the information that defines the shape of
an object or pixels associated with an object. Since the object mask is
tracked and encoded into the bitstream, it is possible to provide various
functionalities based on object.

More specifically, the shape information or object mask is used to indicate the arbitrary shape of an image or video object and the region in which the texture of this object needs to be coded. The binary shape information provides object mask with only two values: transparent or opaque (where transparent means the corresponding pixel is outside of an object and opaque means the corresponding pixel is within the object). FIG. 1(a) shows such an arbitrary shaped object 100 and FIG. 1(b) shows the corresponding binary object mask 110 that identifies the shape and texture region of the object. Although the arbitrary shaped object 100 contains specific texture information, illustrated by the different gray-scale shading, such specific texture information is not captured by the object mask. Only the shape information and whether a pixel is within or without an object is provided by the object mask.

When scalability is required, the mask (i.e., shape of the object) is typically decomposed into a plurality of different spatial resolutions (levels of resolution), such that the encoder will also encode the mask at different spatial resolutions into the encoded bitstream. However, since numerous decompositions methods are available, the encoding efficiency of the encoder varies depending on the decomposition method that is employed. Additionally, if the decomposition method is modified, it is often necessary or desirable to also alter the mask encoding method to better match the decomposition method, thereby increasing overall coding efficiency. Unfortunately, such modification to the encoder is costly, complex, and time consuming.

Therefore, a need exists in the art for a generic spatially-scalable shape encoding method and apparatus that is capable of handling different decomposition methods, while maximizing coding efficiency of the encoder.

SUMMARY OF THE INVENTION

In the present invention, an embodiment of a generic spatially-scalable shape encoding apparatus and concomitant method for handling different mask decomposition methods, while maximizing coding efficiency of the encoder, is disclosed. The present generic spatially-

scalable shape encoding applies three encoding steps to maximize the coding efficiency of the encoder, i.e., mask mode encoding, base mask layer coding and enhancement mask layer coding.

More specifically, an image frame (top level) having at least one
5 object is initially segmented into a plurality of blocks or regions. For the purpose of mask generation, each block is assigned a mode or symbol to indicate whether it is “opaque”, “transparent” or “border”. The modes for the entire top level mask is then encoded into the bitstream.

In turn, the top level mask is decomposed into a plurality of mask
10 layers or mask levels using any shape or mask decomposition methods. The lowest mask layer, i.e., base mask layer, is then encoded into the bitstream.

Next, mask layers that are above the base layer are then
hierarchically and/or contextually encoded using information from an
15 immediate lower mask layer. Namely, each layer or “enhancement mask layer” is encoded using information that is derived from a mask layer that is immediately below the present mask layer of interest. In this manner, a generic spatially-scalable shape encoding apparatus and concomitant
20 method is provided that is capable of handling different shape or mask decomposition methods, while maximizing coding efficiency of the encoder.

BRIEF DESCRIPTION OF THE DRAWINGS

The teachings of the present invention can be readily understood by
25 considering the following detailed description in conjunction with the accompanying drawings, in which:

FIG. 1 illustrates a block diagram of the correlation between an arbitrary shaped object and its corresponding object mask;

FIG. 2 illustrates a block diagram of the correlation between a
30 higher mask layer and its corresponding decomposed lower mask layer via decomposition by subsampling;

FIG. 3 illustrates a block diagram of the correlation between a higher mask layer and its corresponding decomposed lower mask layer via decomposition by majority decision;

FIG. 4 illustrates a block diagram of the correlation between a higher mask layer and its corresponding decomposed lower mask layer via decomposition by OR-ING decision;

5 FIG. 5 illustrates a block diagram of the correlation between a higher mask layer and its corresponding decomposed lower mask layer via decomposition by odd symmetric filters;

FIG. 6 illustrates a block diagram of the correlation between a higher mask layer and its corresponding decomposed lower mask layer via decomposition by even symmetric filters;

10 FIG. 7 illustrates a block diagram of the relative positions of context elements for block mode coding;

FIG. 8 illustrates a block diagram of the relative positions of context elements for base layer coding;

15 FIG. 9 illustrates a block diagram of the relative positions of context elements for enhancement layer coding;

FIG. 10 illustrates a flowchart of a method for shape or mask encoding of the present invention;

FIG. 11 illustrates a flowchart of a detailed method for shape or mask encoding of the present invention;

20 FIG. 12 illustrates a block diagram of an encoding and decoding system of the present invention;

FIG. 13 illustrates a two-pass prediction-based enhancement layer coding method;

25 FIG. 14 illustrates a block diagram of the relative positions of context elements for a first pass enhancement layer coding;

FIG. 15 illustrates a block diagram of the relative positions of context elements in enhancement layer coding for encoding a first pixel in the half-higher spatial layer;

30 FIG. 16 illustrates a block diagram of the relative positions of context elements in enhancement layer coding for encoding a second pixel in the half-higher spatial layer;

FIG. 17 illustrates a block diagram of the relative positions of context elements for a second pass enhancement layer coding;

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FIG. 18 illustrates a block diagram of the relative positions of context elements in enhancement layer coding for encoding a first pixel in the current spatial layer;

FIG. 19 illustrates a block diagram of the relative positions of
5 context elements in enhancement layer coding for encoding a second pixel in the current spatial layer;

FIG. 20 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a binary context model for a first pixel $A(2i,2j)$;

10 FIG. 21 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a binary context model for a second pixel $A(2i,2j+1)$;

FIG. 22 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a binary context
15 model for a third pixel $A(2i+1,2j)$;

FIG. 23 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a binary context model for a fourth pixel $A(2i+1,2j+1)$;

20 FIG. 24 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a second binary context model for a first pixel $A(2i,2j)$;

FIG. 25 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a second binary context model for a second pixel $A(2i,2j+1)$;

25 FIG. 26 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a second binary context model for a third pixel $A(2i+1,2j)$;

FIG. 27 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a second binary
30 context model for a fourth pixel $A(2i+1,2j+1)$;

FIG. 28 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a third binary context model for a first pixel $A(2i,2j)$;

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FIG. 29 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a third binary context model for a second pixel $A(2i, 2j+1)$;

FIG. 30 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a third binary context model for a third pixel $A(2i+1, 2j)$; and

FIG. 31 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a third binary context model for a fourth pixel $A(2i+1, 2j+1)$.

To facilitate understanding, identical reference numerals have been used, where possible, to designate identical elements that are common to the figures.

DETAILED DESCRIPTION

Shape coding is an important part of object-oriented image and video coding. The shape information or object mask is used to indicate the arbitrary shape of an image or video object and the region in which the texture of this object needs to be coded. The shape information (e.g., binary shape information) provides object mask with only two values: transparent or opaque (where transparent means the corresponding pixel is outside of an object and opaque means the corresponding pixel is within the object) as discussed above in FIG. 1.

For applications that do not require spatial scalability, a standard non-scalable binary shape coding is an effective method for encoding the object mask. However, some standards, such as MPEG-4, have also adopted the standard binary shape coding to object-oriented video coding. Since the standard binary shape coding method is not spatially scalable, the decoder needs to retrieve an undesirable amount of extra information in order to properly decode a scaled version of the original full-resolution frame, regardless of the spatial level or spatial resolution. In other words, the encoder must transmit the full-resolution shape information to the decoder and the decoder must decode the full-resolution shape information to obtain the correct full-resolution object mask. Then, the decoder must first decompose the full-resolution object mask into masks at

different spatial resolutions before it can correctly decode the coded coefficients in the bitstream for a desired scaled version of the original full-resolution frame. Unfortunately, this would require both more transmission bandwidth and decoding time.

5 Furthermore, the shape (or mask) decomposition schemes that generate different spatial layers of mask may vary from application to application. For example, in some applications, each lower layer can be achieved by subsampling of every other pixel in both horizontal and vertical directions of the rectangular mask in a higher layer as shown in
10 FIG. 2. Namely, a higher mask layer 200 is decomposed into a lower mask layer 210 by sampling in both directions by a factor of two.

Alternatively, FIG. 3 illustrates a block diagram of a mask decomposition that is based on majority decision. Namely, the lower layer of mask is formed by setting the mask value of the each pixel to that of the
15 majority of the pixels in the 2x2 region in a higher layer. For example, a 2x2 region 300 has four transparent pixels, thereby generating a single transparent pixel 300a in the lower mask layer. In contrast, a 2x2 region 310 has two transparent pixels and two opaque pixels, thereby generating a single opaque pixel 310a in the lower mask layer, where the majority
20 rule in this example defines an opaque pixel for the condition where two or more pixels are opaque in the corresponding higher mask level.

Alternatively, FIG. 4 illustrates a block diagram of a mask decomposition that is based on "OR-ing" decision. Namely, the mask value of each pixel in the lower layer is set to opaque whenever there is at
25 least an opaque pixel in the corresponding 2x2 region in a higher layer. For example, a 2x2 region 400 has four transparent pixels, thereby generating a single transparent pixel 400a in the lower mask layer. In contrast, a 2x2 region 410 has three transparent pixels and one opaque pixel, thereby generating a single opaque pixel 410a in the lower mask
30 layer, where the OR-ing rule in this example defines an opaque pixel in the lower mask layer for the condition where at least one pixel is opaque in the corresponding higher mask layer.

Furthermore, for the arbitrary shape wavelet coding method adopted in the MPEG-4 standard, two additional mask decomposition

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methods are proposed, which correspond to two different filter types: "odd symmetric filters" and "even symmetric filters". For both types of filters, the mask decomposition is achieved by performing horizontal and vertical 1-D mask decomposition.

5 FIG. 5 illustrates a block diagram of a mask decomposition that is based on odd symmetric filters. More specifically, for the odd symmetric filters case, the 1-D decomposition begins by subsampling every even position mask value into low subband and every odd position mask value into high subband. If there is an isolated pixel at the odd position, then the mask values at the corresponding position at low subband and high subband are swapped.

10 FIG. 6 illustrates a block diagram of a mask decomposition that is based on even symmetric filters. More specifically, for the even symmetric filters case, the 1-D decomposition begins by subsampling every even position mask value into low subband and every odd position mask value into high subband. If a segment starts at odd position, then the mask values at the start position at low subband and high subband are swapped.

15 As discussed above, since numerous decomposition methods are available, the encoding efficiency of the encoder varies depending on the decomposition method that is employed. Additionally, if the decomposition method is modified, it is often necessary or desirable to also alter the mask encoding method to better match the decomposition method, thereby increasing overall coding efficiency. Thus, it is desirable to have a generic scalable shape mask coding method that is capable of

20 handling any decomposition method, including but not limited to, all the decomposition methods mentioned above in a generic manner. Moreover, the mask decomposition method used should correspond to the specific decomposition method used for texture coding to obtain true scalability.

25 In the present invention, a new generic spatially-scalable shape coding method is disclosed that is independent of the mask decomposition scheme. It has been observed that the present scalable shape coding method has better overall coding efficiency than the non-scalable coding scheme adopted in the current proposed MPEG-4 standard.

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FIG. 12 illustrates a coding and decoding system 1200 of the present invention. The present coding and decoding system 1200 comprises an encoder 1210 and a decoder 1270. In the preferred embodiment, the encoder 1210 comprises a shape coder 1211 and a texture coder 1220. The shape coder 1211 is tasked with generating and coding the shape information, e.g., object mask, whereas the texture coder 1220 is tasked with the encoding of the luminance and chrominance variations of the regions bounded by the object mask.

More specifically, input image signal is received on path 1205 by both coders 1211 and 1220. The input image signal can be an input video image (image sequence) which is digitized and represented as a luminance and two color difference signals.

The shape coder 1211 operates to extract shape information from the input image, e.g., detecting one or more objects, generating object masks, decomposing object masks, and/or coding of object masks. As such, the present generic spatially-scalable shape coding method is implemented in shape coder 1211. It should be noted that the input image signal may already contain "object based" information, such that one or more shape processing steps can be omitted. For example, if the input image signal contains VOP information, segmentation processing can be omitted since the objects are already defined for the shape coder 1211.

The texture coder 1220 may comprise a motion estimation module 1230, a motion compensation module 1229, a transform module (discrete cosine transform (DCT) or discrete wavelet transform (DWT))1222, a quantization (Q) module 1223, an entropy coding module 1224, e.g., variable length coding (VLC) module, a buffer 1225, an inverse quantization (Q^{-1}) module 1226, an inverse transform (DCT^{-1} or DWT^{-1}) transform module 1227, a subtractor 1221 and a summer 1234. It should be noted that the texture coder 1220 is illustrated as an example and the present invention is not limited to any particular texture coder.

In operation, the input image signal is received into motion estimation module 1230 for estimating motion vectors. In fact, the motion estimation module 1230 may utilize the shape information received from the shape coder in its motion estimation processing. The motion vectors

are received by the motion compensation module 1229 for generating a prediction that uses motion vectors to provide offsets into the past and/or future reference frames containing previously decoded sample values that are used to form the prediction error.

5 A motion compensated prediction (predicted image) is generated on path 1236 and is subtracted via subtractor 1221 from the input image on path 1205 to form an error signal or predictive residual signal on path 1231. A spatial transform module 1222 is then applied to generate transform coefficients which can be manipulated for the purpose of
10 removing spatial redundancy.

 The resulting transform coefficients are received by quantization module 1223 where the transform coefficients are quantized. Next, the resulting quantized coefficients are received by variable length coding (VLC) module 1224 via signal connection 1235, where the quantized
15 coefficients are entropy coded and are received into a "First In-First Out" (FIFO) buffer 1225 for transmission or storage.

 Additionally, the resulting quantized coefficients from the quantization module 1223 are also received by the inverse quantization module 1226 via signal connection 1233. The resulting dequantized
20 coefficients are passed to the inverse transform module 1227 where inverse transform is applied to produce the decoded error signal. This error signal is added back to the prediction signal from the motion compensation module via summer 1234 to produce a decoded reference picture (reconstructed image).

25 The encoded bitstreams from coders 1211 and 1220 are then received and multiplexed by the transport stream multiplexer 1240 to produce a transport stream. The transport stream is transmitted over a communication channel 1250, which may further incorporate separate channel specific encoder and decoder (not shown). Next, the transport
30 stream is demultiplexed and decoded by a transport stream demultiplexor 1260, where the elementary streams serve as inputs to video decoder 1270, whose output is a decoded video signal on path 1290.

It should be noted that although the present invention is described below with respect to an encoding method and apparatus, a corresponding and

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complementary decoding process is performed via a complementary set of a shape decoder 1274 and a texture decoder 1272.

Furthermore, FIG. 12 illustrates the present encoder 1210 and decoder 1270 as capable of being implemented within a general purpose computer having various input/output devices, e.g., a keyboard, a mouse, an audio recorder, a camera, a camcorder, a video monitor, any number of imaging devices or storage devices, including but not limited to, a tape drive, a floppy drive, a hard disk drive or a compact disk drive (not shown). Namely, the general purpose computer may comprise a central processing unit (CPU) (not shown), a memory (not shown) and the encoder 1210 for encoding an image, video and/or audio signal in accordance with the methods described below.

The encoder 1210 can be a physical device, which is coupled to the CPU through a communication channel. Alternatively, the encoder 1210 can be represented by a software application (or a combination of software and hardware, e.g., using application specific integrated circuits (ASIC)), where the software is loaded from a storage medium, (e.g., a magnetic or optical drive or diskette) and operated by the CPU in the memory of the computer. As such, the encoder itself and the methods executed by the encoder of the present invention can be stored on a computer readable medium.

Similarly, the decoder 1270 can also be a physical device, which is coupled to the CPU through a communication channel. Alternatively, the decoder 1270 can be represented by a software application (or a combination of software and hardware, e.g., using application specific integrated circuits (ASIC)), where the software is loaded from a storage medium, (e.g., a magnetic or optical drive or diskette) and operated by the CPU in the memory of the computer. As such, the decoder itself and the methods executed by the decoder of the present invention can also be stored on a computer readable medium.

FIG. 10 illustrates a top level flowchart of a generic shape or mask encoding method 1000 of the present invention. The method 1000 starts in step 1005 and proceeds to step 1010 where mode coding is applied to the shape or object mask.

More specifically, in step 1010, a full-resolution image frame having at least one object is initially segmented into a plurality of blocks or regions. Although the terms "block" and "region" are specifically defined below in different embodiments, it should be understood that these terms
5 can be interpreted broadly in this specification to be as small as a single pixel or as large as the entire input image frame. For the purpose of mask generation, each block is assigned a mode or symbol to indicate whether it is "opaque", "transparent" or "border". The modes for the entire mask are then encoded into the bitstream.

10 In step 1020, method 1000 decomposes the "top level" or full-resolution mask into a plurality of layers or mask levels using any shape or mask decomposition methods, e.g., any of the decomposition methods as discussed above in FIGs. 2-6. The lowest mask layer, i.e., "base mask layer", is then encoded into the bitstream in step 1020.

15 In step 1030, method 1000 hierarchically and contextually encodes mask layers that are above the base mask layer by using information from an immediate lower mask layer. Namely, each layer above the base mask layer (or "enhancement mask layer") is encoded using information that is derived from a mask layer that is immediately below the present mask
20 layer of interest. In this manner, a generic spatially-scalable shape encoding method is provided that is capable of handling different shape or mask decomposition methods, while maximizing coding efficiency of the encoder.

The present invention is now described in detail below with
25 reference to FIGs. 7, 8, 9 and 11. FIG. 11 illustrates a flowchart of a detailed method 1100 for generic spatially scalable shape or mask encoding, that is independent of the shape decomposition method.

Method 1100 starts in step 1105 and proceeds to step 1110, where an object mask is divided or defined in accordance with a plurality of blocks or
30 regions. Assume "L" levels of mask decomposition is to be performed on the original input or full-resolution object mask. Then, method 1100 divides the object mask into blocks of $2^N \times 2^N$ pixels, where N is equal to or greater than L.

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In step 1120, if the size of the object mask is not multiples of 2^N , then method 1100 may pad the object mask with zeros in the proper direction(s) to make the object size multiples of 2^N .

In step 1130, method 1100 assigns mask symbols or modes to each of
 5 the blocks. Namely, for each block of $2^N \times 2^N$ pixels, if all its pixels have mask values of 1's, then method 1100 marks the block with symbol "ALL-
 Opaque" (mode=1). If all its pixels have mask values of 0's, then method 1100 marks the block with symbol "ALL-Transparent" (mode=0).
 Otherwise, method 1100 marks the block with symbol "Border" (mode=2),
 10 i.e., the block contains both 1's and 0's indicating the border of an object .

In step 1140, method 1100 then encodes the mask symbols. In the preferred embodiment, each of these block modes or symbols (M_{ij}) is encoded using context-based arithmetic coding based on the following context:

$$15 \quad context_0 = S_3 * 27 + S_2 * 9 + S_1 * 3 + S_0, \quad (1)$$

where $context_0$ is the context for the current block mode to be coded, $S_3=M_{(i-1)(j-1)}$, $S_2=M_{(i-1)j}$, $S_1=M_{(i-1)(j+1)}$, $S_0=M_{ij-1}$, and i and j are the row index and
 20 column index of the blocks, respectively. Namely, using $context_0$ as defined by equation (1) to switch a variable length code table to encode the current mode. If any of the context element is outside the rectangular mask, ALL-Transparent symbol is used to replace it. To clarify the context elements of equation (1), FIG. 7 illustrates the context
 25 construction, where the block 700 with a question mark indicates the block whose mode is to be encoded.

Alternatively, in step 1140, method 1100 can encode the mode for the block (M_{ij}) using binary context-based arithmetic coding method. Namely, the 3-ary block mode symbol is first decomposed into binary symbol(s).
 30 Binary variables class and type are used to represent a 3-ary block mode.

More specifically, the three mode symbols are classified into 2 classes: "Uniform" (All-Transparent, and All-Opaque) Or "Non-uniform" (Border). If the symbol belongs to the Uniform class, additional type information is used to differentiate All-Transparent or All-Opaque modes.

The additional information "type" has two possible values: Transparent (0) or Opaque (1). If the symbol belongs to the Non-uniform class, no additional information is needed. The mode symbol can then be represented as:

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$$S = (\text{class} == \text{UNIFORM})? ((\text{type} == \text{TRANSPARENT})? 0:1):2 \quad (1a)$$

The binary variables class and type are then encoded using the same binary arithmetic coder as discussed above with the context as described in equation (1). Specifically, two context based binary probability models for "class" and "type", respectively can be employed. For each mode symbol, the "class" is first encoded using a binary arithmetic coder. If the "class" is "Uniform", then "type" is also coded using a binary arithmetic coder with the corresponding probability model. If the "class" is "Nonuniform", then the current mode symbol coding is finished and the encoder will proceed to the next mode symbol for the next block. Table A-I(a) and Table A-I(b) in the Appendix provide the context based probability tables for the variables "class" and "type", respectively.

Returning to FIG. 11, in step 1150, method 1100 decomposes the full-resolution or input object mask into a plurality of mask layers. Namely, any desired mask decomposition scheme can be used to decompose the object mask into L levels of spatial layers.

For example, in one embodiment, denote each layer as Λ_n , where $0 \leq n \leq L$. Λ_0 denotes the full resolution object mask and Λ_L denotes the base mask layer (lowest spatial layer). For each layer, mark all pixels corresponding to the ALL-Transparent or ALL-Opaque blocks as "Not-Coded" since its value can be easily filled according to the block mode, and mark all other pixels to "To-Be-Coded".

In step 1160, method 1100 encodes the base mask layer. More specifically, for the base mask layer (lowest spatial layer), the mask value (m_y^L) of pixels marked as "To-Be-Coded" are encoded in raster scan order, using context based arithmetic coding. The context can be constructed as follows:

$$\text{context}_1 = (C_9 \ll 9) \mid (C_8 \ll 8) \mid (C_7 \ll 7) \mid (C_6 \ll 6) \mid (C_5 \ll 5) \mid (C_4 \ll 4) \mid (C_3 \ll 3) \mid (C_2 \ll 2) \mid (C_1 \ll 1) \mid C_0 \quad (2)$$

where “ \ll ” is a left-shift operation and “ \mid ” is a bit wise logical OR

5 operation, $C_9 = m^L_{(i-2)(j-1)}$, $C_8 = m^L_{(i-2)j}$, $C_7 = m^L_{(i-2)(j+1)}$, $C_6 = m^L_{(i-1)(j-2)}$, $C_5 = m^L_{(i-1)(j-1)}$, $C_4 = m^L_{(i-1)j}$, $C_3 = m^L_{(i-1)(j+1)}$, $C_2 = m^L_{(i-1)(j+2)}$, $C_1 = m^L_{i(j-2)}$, $C_0 = m^L_{i(j-1)}$,

context₁ is the context for the current base-layer mask value to be coded, i and j denotes the current row and column indices of the mask value to be coded. In the case where the position of a context element (C_k) is outside
10 the lowest layer’s rectangular boundary, C_k is always set to zero in the construction of the context. To clarify the context elements of equation (2), FIG. 8 illustrates the context construction, where the pixel 800 with a question mark indicates the base-layer mask value to be encoded.

In step 1165, method 1100 queries whether a higher mask layer
15 needs to be coded. If the query is positively answered, then method 1100 proceeds to step 1170. If the query is negatively answered, then method 1100 ends in step 1180.

In step 1170, method 1100 encodes the next mask layer, i.e., enhancement layer coding. More specifically, method 1100 employs
20 hierarchical and contextual encoding, where the mask of each spatial layer Λ_n is encoded in accordance with the previous lower spatial layer Λ_{n+1} , where $0 \leq n < L$.

Namely, for each 2x2 non-overlapped subblock, V^n , in the spatial layer Λ_n that is marked “To-Be-Coded”, form a variable that have 16
25 different values as follows:

$$V^n = m^n_{(2i)(2j)} * 8 + m^n_{(2i)(2j+1)} * 4 + m^n_{(2i+1)(2j)} * 2 + m^n_{(2i+1)(2j+1)} \quad (3)$$

where i and j are row and column indices which this 2x2 subblock
30 corresponding to in the previous lower spatial layer Λ_{n+1} . V^n is then encoded using context-based arithmetic coding. The context of the arithmetic coder can be constructed as follows:

$$\text{context}_2 = (T_7 \ll 7) \mid (T_6 \ll 6) \mid (T_5 \ll 5) \mid (T_4 \ll 4) \mid (T_3 \ll 3) \mid (T_2 \ll 2) \mid (T_1 \ll 1) \mid (T_0) \quad (4)$$

where “ \ll ” is a left-shift operation and “ \mid ” is a bit wise logical OR

5 operation, $T_7 = m^n_{(2i-1)(2j)}$, $T_6 = m^n_{(2i-1)(2j+1)}$, $T_5 = m^n_{(2i)(2j-1)}$, $T_4 = m^n_{(2i+1)(2j-1)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i)(j+1)}$, $T_1 = m^{n+1}_{(i+1)(j)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, $m^n_{(x)(y)}$ denotes the mask value at position (x,y) in spatial layer Λ_n , 910. It should be noted that in the above context, mask values from lower spatial layer Λ_{n+1} , 900, are used in the construction of the context. Again, for those context elements that are
10 outside the layer boundary, zeros are used instead to form the context.

To clarify the context elements of equation (4), FIG. 9 illustrates the context construction, where the pixels 912, 914, 916, and 918 with question marks indicate the pixels in current spatial layer Λ_n 910 whose mask values are to be encoded. Namely, FIG. 9 illustrates the construction of
15 this context from both the lower spatial layer Λ_{n+1} 900 and from a current spatial layer Λ_n 910.

Alternatively, two additional embodiments are now described below for implementing enhancement layer coding: a two-pass coding approach and a binary arithmetic coding approach. Advantages of the two-pass
20 coding approach include its ability in supporting different wavelet filters for both horizontal and vertical directions, its simplified context models and its compatibility with the present scalable shape coding method as proposed in the MPEG-4 video object coding standard. In contrast, the binary arithmetic coding approach is advantageous in simplifying the
25 implementation of the shape coder 1211. Thus, the implementation of the enhancement layer coding can be selected in accordance with the need of a particular application.

Two-Pass Enhancement Layer Coding

30 The two-pass enhancement layer coding can be implemented in step 1170, as shown in FIG. 13. In the first pass, a “half-higher” spatial layer $\Lambda_{n+1/2}$ 1310 is encoded based on a previous lower spatial layer Λ_{n+1} 1300. In the second pass, the current spatial layer Λ_n 1320 is encoded based on the

half-higher spatial layer $\Lambda_{n+1/2}$ 1310. The half-higher spatial layer $\Lambda_{n+1/2}$ 1310 is defined as the lower (left) half of the mask after the horizontal analysis from the higher layer Λ_n 1320. In other words, the half-higher spatial layer $\Lambda_{n+1/2}$ 1310 is the result of applying horizontal decomposition (i.e., applying filter in the horizontal direction only), where the left half of the results would be the horizontal low pass.

It should be noted that since the present invention is a prediction based approach, it is able to handle both linear subsampling as well as non-linear subsampling based mask decomposition. Therefore, the present invention provides a unified and generic scalable shape coding framework for all the cases including those cases needed in MPEG-4. This alternative two-pass approach can be referred to as "1-2-4" (or One-Two-Four) prediction-based scalable shape coding. Additionally, an advantage of this method is that it can support different decomposition filters in horizontal and vertical directions and will operate for block-based coding as well.

First Pass: Coding half-higher spatial layer $\Lambda_{n+1/2}$ from lower spatial layer

Λ_{n+1}

In the first pass, two pixels in each 1×2 (one pixel in the horizontal direction and two pixels in the vertical direction) non-overlapped subblock in the raster-scan order in the half-higher spatial layer that is marked "To-Be-Coded" (e.g., corresponding to a BORDER block), are coded separately. More specifically, the two pixels $m^{n+1/2}_{(2i)(j)}$ and $m^{n+1/2}_{(2i+1)(j)}$, where i and j are row and column indices to which this 1×2 subblock corresponds in the lower spatial layer Λ_{n+1} are coded separately using the context based arithmetic coding schemes described below.

FIG. 14 illustrates a block diagram of the relative positions of context elements for enhancement layer coding. Namely, FIG. 14 illustrates the related pixels and their labels used in the context based arithmetic coding from a lower spatial layer 1400 to a half-higher spatial layer 1410. The related pixels and their labels are as follows: where

$T_9 = m^{n+1/2}_{(2i-1)(j)}$, $T_8 = m^{n+1/2}_{(2i-1)(j+1)}$, $T_7 = m^{n+1/2}_{(2i+1)(j-1)}$, $T_6 = m^{n+1/2}_{(2i)(j-1)}$, $T_5 = m^{n+1}_{(i)(j)}$,
 $T_4 = m^{n+1}_{(i)(j+1)}$, $T_3 = m^{n+1}_{(i+1)(j)}$, $T_2 = m^{n+1}_{(i+1)(j+1)}$, $T_{10} = m^{n+1}_{(i+1)(j-1)}$, $T_1 = m^{n+1/2}_{(2i)(j)}$,
 $T_0 = m^{n+1/2}_{(2i+1)(j)}$, and where $m^z_{(x)(y)}$ denotes the mask value at position (x, y)
 in spatial layer Λ_z . T_6 through T_9 are the corresponding already

5 encoded/decoded pixels in the half-higher spatial layer $\Lambda_{n+1/2}$, and T_5
 through T_2 and T_{10} are corresponding pixels in the lower spatial layer Λ_{n+1}
 (1400). T_1 (1412) and T_0 (1414), are the pixels to be coded in the half-higher
 spatial layer $\Lambda_{n+1/2}$ (1410).

FIG. 15 illustrates a block diagram of the relative positions of
 10 context elements in enhancement layer coding for encoding a first pixel
 1412 in the half-higher spatial layer 1510. Namely, FIG. 15 illustrates the
 context used for encoding the pixel $T_1 = m^{n+1/2}_{(2i)(j)}$, i.e., where the question
 mark indicates the pixel whose mask value is to be encoded as follows:

$$\begin{aligned}
 15 \quad \text{Context}_3 = & (T_9 < 7) \mid (T_8 < 6) \mid (T_7 < 5) \mid (T_6 < 4) \mid (T_5 < 3) \mid (T_4 < 2) \mid (T_3 < 1) \mid \\
 & (T_2) \quad (5)
 \end{aligned}$$

Table A-II(a) and Table A-II(b) in the Appendix provide the context based
 probability tables for T_1 corresponding to odd-symmetric wavelet filter and
 20 even symmetric wavelet filter, respectively.

FIG. 16 illustrates a block diagram of the relative positions of
 context elements in enhancement layer coding for encoding a second pixel
 1414 in the half-higher spatial layer 1610. Namely, FIG. 16 illustrates the
 context used for encoding the pixel $T_0 = m^{n+1/2}_{(2i+1)(j)}$, i.e., where the question
 25 mark indicates the pixel whose mask value is to be encoded as follows:

$$\begin{aligned}
 \text{Context}_4 = & (T_1 < 7) \mid (T_{10} < 6) \mid (T_7 < 5) \mid (T_6 < 4) \mid (T_5 < 3) \mid (T_4 < 2) \mid (T_3 < 1) \mid \\
 & (T_2) \quad (6)
 \end{aligned}$$

30 It should be noted that in FIG. 16 the pixel T_1 is no longer illustrated
 with a “?” since its value is now known. Table A-III(a) and Table A-III(b)
 in the Appendix provide the context based probability tables for T_0

corresponding to odd-symmetric wavelet filter and even symmetric wavelet filter, respectively.

Second Pass: Coding current spatial layer Λ_n from half-higher layer $\Lambda_{n+1/2}$

5 The second pass can be achieved by transposing both the half-higher layer and the current mask layer and applying the same procedure of the first pass to encode the current layer mask. Alternatively, the second pass coding can be implemented with no transposing of mask. The two pixels in each 2x1 (two pixels in the horizontal direction and one pixel in the vertical direction) non-overlapped subblock in the vertical-first raster-scan order (that is, the subblocks are scanned in vertical direction first from top to bottom) in the current spatial layer that is marked "To-Be-Coded" (e.g., corresponding to a BORDER block), are coded separately. More specifically, the two pixels $m^n_{(i)(2j)}$ and $m^n_{(i)(2j+1)}$, where i and j are row and column indices to which this 2x1 subblock corresponds in the half-higher spatial layer $\Lambda_{n+1/2}$ are coded separately using the context based arithmetic coding schemes described below.

FIG. 17 illustrates a block diagram of the relative positions of context elements for a second pass enhancement layer coding. Namely, FIG. 17 illustrates the related pixels and their labels used in the context based arithmetic coding from a half-higher spatial layer 1700 to a current spatial layer 1710. The related pixels and their labels are as follows: where $T_9 = m^n_{(i)(2j-1)}$, $T_8 = m^n_{(i+1)(2j-1)}$, $T_7 = m^n_{(i-1)(2j+1)}$, $T_6 = m^n_{(i-1)(2j)}$, $T_5 = m^{n+1/2}_{(i)(j)}$, $T_4 = m^{n+1/2}_{(i+1)(j)}$, $T_3 = m^{n+1/2}_{(i)(j+1)}$, $T_2 = m^{n+1/2}_{(i+1)(j+1)}$, $T_{10} = m^{n+1/2}_{(i-1)(j+1)}$, $T_1 = m^n_{(i)(2j)}$, $T_0 = m^n_{(i)(2j+1)}$, and where $m^z_{(x)(y)}$ denotes the mask value at position (x, y) in spatial layer Λ_z . T_6 through T_9 are the corresponding already encoded/decoded pixels in a current layer and T_5 through T_{10} are corresponding pixels in the half-higher spatial layer $\Lambda_{n+1/2}$ (1700). T_1 (1712) and T_0 (1714), are the pixels to be coded in the current spatial layer $\Lambda_{n+1/2}$ (1710).

FIG. 18 illustrates a block diagram of the relative positions of context elements in enhancement layer coding for encoding a first pixel 1712 in the current spatial layer 1810. Namely, FIG. 18 illustrates the

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662750, 662756

context used for encoding the pixel $T_1 = m^n_{(i)(2j)}$, i.e., where the question mark indicates the pixel whose mask value is to be encoded as follows:

$$\text{Context}_5 = (T_9 < 7) \mid (T_8 < 6) \mid (T_7 < 5) \mid (T_6 < 4) \mid (T_5 < 3) \mid (T_4 < 2) \mid (T_3 < 1) \mid (T_2) \quad (7)$$

Table A-II(a) and Table A-II(b) in Appendix give the context based probability tables for T_1 corresponding to odd-symmetric wavelet filter and even symmetric wavelet filter, respectively.

FIG. 19 illustrates a block diagram of the relative positions of context elements in enhancement layer coding for encoding a second pixel 1714 in the current spatial layer 1910. Namely, FIG. 19 illustrates the context used for encoding the pixel $T_0 = m^n_{(i)(2j+1)}$, i.e., where the question mark indicates the pixel whose mask value is to be encoded as follows:

$$\text{Context}_6 = (T_1 < 7) \mid (T_{10} < 6) \mid (T_7 < 5) \mid (T_6 < 4) \mid (T_5 < 3) \mid (T_4 < 2) \mid (T_3 < 1) \mid (T_2) \quad (8)$$

Again, it should be noted that in FIG. 19 the pixel T_1 is no longer illustrated with a "?" since its value is now known. Table A-III(a) and Table A-III(b) in Appendix give the context based probability tables for T_0 corresponding to odd-symmetric wavelet filter and even symmetric wavelet filter, respectively.

It should be noted that in the above contexts, mask values from lower spatial layer Λ_{n+1} and half-higher spatial layer $\Lambda_{n+1/2}$ are used in the construction of the context, where the implicit prediction occurs. Again, for those context elements that are outside of the layer's boundary, zeros are used instead to form the context.

It should be noted that all the probability tables in the Appendix give the probability of zeros under given contexts. Namely, the probability tables are normalized to within range [0, 65536]. However, there are three special cases:

1) Probability of zero under certain context is zero. This means that under that context, it is certain that the coded value can only be one. No bits need to be encoded.

2) Probability of zero under certain context is 65536. This means that under that context it is certain that the coded value can only be zero. No bits need to be encoded.

3) Probability of zero under certain context is 65537. This means that this specific context can never occur. Namely, coding based on such a context is an error of the encoder.

Alternatively, the user can also choose to encode the whole shape in a non-scalable manner. In this case, there is no requirement for a one-to-one correspondence between shape decomposition and texture decomposition. This is a special case of the above method where the shape decomposition level L is set to 0, and there is no enhanced layer coding.

Furthermore, the above frame-based shape coding scheme can be easily extended to block-based coding since the contexts used support such block-based coding. When contexts element at block boundaries are not available, the mask values at the corresponding positions in the predicting layers can be used instead.

Binary Arithmetic Enhancement Layer Coding

In order to simplify the scalable shape coder 1211, binary arithmetic encoding is typically preferred. Specifically, the 2x2 coding group in the enhancement layer is divided into individual pixels. In the present invention, several embodiments of simplified binary context models are described. In these methods, the four pixels in a 2x2 block in the enhancement layer are still scanned at the same time. However, when each 2x2 block is scanned, each of the four pixels is coded separately using different context models. Let denote the 2x2 pixels by its spatial location: $A(2i, 2j)$, $A(2i, 2j+1)$, $A(2i+1, 2j)$, $A(2i+1, 2j+1)$. The following context based binary arithmetic coding methods can also be applied to achieve the same high coding efficiency as described above.

First Binary Embodiment

The difference in this binary arithmetic coding embodiment is that the above context-based arithmetic encoding is changed to a binary representation instead of a multi-symbol representation in coding the enhanced layer. The context construction is similar to that described above in FIG. 9, but now the 2x2 block in the enhancement mask layer is not grouped into a symbol and the pixels in the 2x2 block are coded one by one using a progressive context. The contexts for each of the 2x2 pixels are shown in FIG. 20 to FIG. 23.

FIG. 20 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a binary context model for a first pixel A(2i,2j) 2012 in the first binary embodiment. Specifically, FIG. 20 illustrates the context construction, where the pixel 2012 with the question mark indicates the pixel in current spatial layer Λ_n 2010 whose mask value is to be encoded. Namely, FIG. 20 illustrates the construction of this context from both the lower spatial layer Λ_{n+1} 2000 and from a current spatial layer Λ_n 2010. The context number used by A(2i, 2j) as shown in FIG. 20 can be given as follows:

$$\text{Context}_7 = (T_7 \ll 7) \mid (T_6 \ll 6) \mid (T_5 \ll 5) \mid (T_4 \ll 4) \mid (T_3 \ll 3) \mid (T_2 \ll 2) \mid (T_1 \ll 1) \mid T_0 \quad (9)$$

where “ \ll ” is a left-shift operation and “ \mid ” is a bit wise logical OR

operation, $T_7 = m^n_{(2i-1)(2j)}$, $T_6 = m^n_{(2i-1)(2j+1)}$, $T_5 = m^n_{(2i)(2j-1)}$, $T_4 = m^n_{(2i+1)(2j-1)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i)(j+1)}$, $T_1 = m^{n+1}_{(i+1)(j)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, $m^n_{(x)(y)}$ denotes the mask value at position (x,y) in spatial layer Λ_n , 2010.

FIG. 21 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a binary context model for a second pixel A(2i,2j+1) 2112 in the first binary embodiment. Specifically, FIG. 21 illustrates the context construction, where the pixel 2112 with the question mark indicates the next pixel in the current spatial layer Λ_n 2110 whose mask value is to be encoded. Namely, FIG. 21 illustrates the construction of this context from both the lower spatial layer

Λ_{n+1} 2100 and from a current spatial layer Λ_n 2110. The context number used by $A(2i, 2j+1)$ as shown in FIG. 21 can be given as follows:

$$\text{Context}_8 = (T_8 \ll 8) \mid (T_7 \ll 7) \mid (T_6 \ll 6) \mid (T_5 \ll 5) \mid (T_4 \ll 4) \mid (T_3 \ll 3) \mid (T_2 \ll 2) \mid (T_1 \ll 1) \mid T_0 \quad (10)$$

where “ \ll ” is a left-shift operation and “ \mid ” is a bit wise logical OR operation, $T_8 = m^n_{(2i)(2j)}$, $T_7 = m^n_{(2i-1)(2j)}$, $T_6 = m^n_{(2i-1)(2j+1)}$, $T_5 = m^n_{(2i)(2j-1)}$, $T_4 = m^n_{(2i+1)(2j-1)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i)(j+1)}$, $T_1 = m^{n+1}_{(i+1)(j)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, $m^n_{(x)(y)}$ denotes the mask value at position (x,y) in spatial layer Λ_n , 2110.

FIG. 22 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a binary context model for a third pixel $A(2i+1, 2j)$ 2212 in the first binary embodiment. Specifically, FIG. 22 illustrates the context construction, where the pixel 2212 with the question mark indicates the next pixel in the current spatial layer Λ_n 2210 whose mask value is to be encoded. Namely, FIG. 22 illustrates the construction of this context from both the lower spatial layer Λ_{n+1} 2200 and from a current spatial layer Λ_n 2210. The context number used by $A(2i+1, 2j)$ as shown in FIG. 22 can be given as follows:

$$\text{Context}_9 = (T_9 \ll 9) \mid (T_8 \ll 8) \mid (T_7 \ll 7) \mid (T_6 \ll 6) \mid (T_5 \ll 5) \mid (T_4 \ll 4) \mid (T_3 \ll 3) \mid (T_2 \ll 2) \mid (T_1 \ll 1) \mid T_0 \quad (11)$$

where “ \ll ” is a left-shift operation and “ \mid ” is a bit wise logical OR operation, $T_9 = m^n_{(2i)(2j+1)}$, $T_8 = m^n_{(2i)(2j)}$, $T_7 = m^n_{(2i-1)(2j)}$, $T_6 = m^n_{(2i-1)(2j+1)}$, $T_5 = m^n_{(2i)(2j-1)}$, $T_4 = m^n_{(2i+1)(2j-1)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i)(j+1)}$, $T_1 = m^{n+1}_{(i+1)(j)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, $m^n_{(x)(y)}$ denotes the mask value at position (x,y) in spatial layer Λ_n , 2210.

FIG. 23 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a binary context model for a fourth pixel $A(2i+1, 2j+1)$ 2312 in the first binary embodiment. Specifically, FIG. 23 illustrates the context construction, where the pixel 2312 with the question mark indicates the next pixel in the current spatial layer Λ_n 2310 whose mask value is to be encoded. Namely, FIG. 23 illustrates the construction of this context from both the lower spatial layer

Λ_{n+1} 2300 and from a current spatial layer Λ_n 2310. The context number used by $A(2i+1, 2j+1)$ as shown in FIG. 23 can be given as follows:

$$\begin{aligned} \text{Context}_{10} = & (T_{10} \ll 10) \mid (T_9 \ll 9) \mid (T_8 \ll 8) \mid (T_7 \ll 7) \mid (T_6 \ll 6) \mid (T_5 \ll 5) \\ & \mid (T_4 \ll 4) \mid (T_3 \ll 3) \mid (T_2 \ll 2) \mid (T_1 \ll 1) \mid T_0 \end{aligned} \quad (12)$$

where “ \ll ” is a left-shift operation and “ \mid ” is a bit wise logical OR

operation, $T_{10} = m^n_{(2i+1)(2j)}$, $T_9 = m^n_{(2i)(2j+1)}$, $T_8 = m^n_{(2i)(2j)}$, $T_7 = m^n_{(2i-1)(2j)}$, $T_6 = m^n_{(2i-1)(2j+1)}$,
 $T_5 = m^n_{(2i)(2j-1)}$, $T_4 = m^n_{(2i+1)(2j-1)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i)(j+1)}$, $T_1 = m^{n+1}_{(i+1)(j)}$,
 $T_0 = m^{n+1}_{(i+1)(j+1)}$, $m^n_{(x)(y)}$ denotes the mask value at position (x,y) in spatial
 layer Λ_n , 2310.

Second Binary Embodiment

The second binary embodiment is similar to the above first binary
 embodiment, except the contexts are simplified by taking advantage of less
 correlation between certain pixels. Specifically, FIG. 24 illustrates a block
 diagram of the relative positions of context elements for enhancement
 layer coding using a binary context model for a first pixel $A(2i, 2j)$ 2412 in
 the second binary embodiment. Specifically, FIG. 24 illustrates the
 context construction, where the pixel 2412 with the question mark
 indicates the pixel in current spatial layer Λ_n 2410 whose mask value is to
 be encoded. Namely, FIG. 24 illustrates the construction of this context
 from both the lower spatial layer Λ_{n+1} 2400 and from a current spatial layer
 Λ_n 2410. The context number used by $A(2i, 2j)$ as shown in FIG. 24 can be
 given as follows:

$$\begin{aligned} \text{Context}_{11} = & (T_7 \ll 7) \mid (T_6 \ll 6) \mid (T_5 \ll 5) \mid (T_4 \ll 4) \mid (T_3 \ll 3) \mid (T_2 \ll 2) \mid (T_1 \\ & \ll 1) \mid T_0 \end{aligned} \quad (13)$$

where “ \ll ” is a left-shift operation and “ \mid ” is a bit wise logical OR

operation, $T_7 = m^n_{(2i-1)(2j)}$, $T_6 = m^n_{(2i-1)(2j+1)}$, $T_5 = m^n_{(2i)(2j-1)}$, $T_4 = m^n_{(2i+1)(2j-1)}$, $T_3 = m^{n+1}_{(i)(j)}$,
 $T_2 = m^{n+1}_{(i)(j+1)}$, $T_1 = m^{n+1}_{(i+1)(j)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, $m^n_{(x)(y)}$ denotes the mask value at
 position (x,y) in spatial layer Λ_n , 2410. This context is identical to that of
 equation (9).

FIG. 25 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a binary context model for a second pixel A(2i,2j+1) 2112 in the second binary embodiment. Specifically, FIG. 25 illustrates the context construction, where the pixel 2512 with the question mark indicates the next pixel in the current spatial layer Λ_n 2510 whose mask value is to be encoded. Namely, FIG. 25 illustrates the construction of this context from both the lower spatial layer Λ_{n+1} 2500 and from a current spatial layer Λ_n 2510. The context number used by A(2i, 2j+1) as shown in FIG. 25 can be given as follows:

$$\text{Context}_{12} = (T_6 << 6) \mid (T_5 << 5) \mid (T_4 << 4) \mid (T_3 << 3) \mid (T_2 << 2) \mid (T_1 << 1) \mid T_0 \quad (14)$$

where "<<" is a left-shift operation and "|" is a bit wise logical OR operation, $T_6 = m^n_{(2i)(2j)}$, $T_5 = m^n_{(2i-1)(2j)}$, $T_4 = m^n_{(2i-1)(2j+1)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i)(j+1)}$, $T_1 = m^{n+1}_{(i+1)(j)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, $m^n_{(x)(y)}$ denotes the mask value at position (x,y) in spatial layer Λ_n , 2510.

FIG. 26 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a binary context model for a third pixel A(2i+1,2j) 2612 in the second binary embodiment. Specifically, FIG. 26 illustrates the context construction, where the pixel 2612 with the question mark indicates the next pixel in the current spatial layer Λ_n 2610 whose mask value is to be encoded. Namely, FIG. 26 illustrates the construction of this context from both the lower spatial layer Λ_{n+1} 2600 and from a current spatial layer Λ_n 2610. The context number used by A(2i+1, 2j) as shown in FIG. 26 can be given as follows:

$$\text{Context}_{13} = (T_7 << 7) \mid (T_6 << 6) \mid (T_5 << 5) \mid (T_4 << 4) \mid (T_3 << 3) \mid (T_2 << 2) \mid (T_1 << 1) \mid T_0 \quad (15)$$

where "<<" is a left-shift operation and "|" is a bit wise logical OR operation, $T_7 = m^n_{(2i)(2j)}$, $T_6 = m^n_{(2i)(2j+1)}$, $T_5 = m^n_{(2i)(2j-1)}$, $T_4 = m^n_{(2i+1)(2j-1)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i)(j+1)}$, $T_1 = m^{n+1}_{(i+1)(j)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, $m^n_{(x)(y)}$ denotes the mask value at position (x,y) in spatial layer Λ_n , 2610.

FIG. 27 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a binary context model for a fourth pixel $A(2i+1, 2j+1)$ 2712 in the second binary embodiment. Specifically, FIG. 27 illustrates the context construction, where the pixel 2712 with the question mark indicates the next pixel in the current spatial layer Λ_n 2710 whose mask value is to be encoded. Namely, FIG. 27 illustrates the construction of this context from both the lower spatial layer Λ_{n+1} 2700 and from a current spatial layer Λ_n 2710. The context number used by $A(2i+1, 2j+1)$ as shown in FIG. 27 can be given as follows:

$$\text{Context}_{14} = (T_6 \ll 6) \mid (T_5 \ll 5) \mid (T_4 \ll 4) \mid (T_3 \ll 3) \mid (T_2 \ll 2) \mid (T_1 \ll 1) \mid T_0 \quad (16)$$

where “ \ll ” is a left-shift operation and “ \mid ” is a bit wise logical OR operation, $T_6 = m^n_{(2i)(2j)}$, $T_5 = m^n_{(2i)(2j+1)}$, $T_4 = m^n_{(2i+1)(2j)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i)(j+1)}$, $T_1 = m^{n+1}_{(i+1)(j)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, $m^n_{(x)(y)}$ denotes the mask value at position (x, y) in spatial layer Λ_n , 2710.

Third Binary Embodiment

The third binary embodiment is similar to the above second binary embodiment, except the contexts are further simplified because of less correlation between certain pixels. Additionally, this third binary embodiment can take advantage of the symmetric feature of the shape decomposition methods in the horizontal and vertical directions.

Specifically, FIG. 28 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a binary context model for a first pixel $A(2i, 2j)$ 2812 in the third binary embodiment. Specifically, FIG. 28 illustrates the context construction, where the pixel 2812 with the question mark indicates the pixel in current spatial layer Λ_n 2810 whose mask value is to be encoded. Namely, FIG. 28 illustrates the construction of this context from both the lower spatial layer Λ_{n+1} 2800 and from a current spatial layer Λ_n 2810. The context number used by $A(2i, 2j)$ as shown in FIG. 28 can be given as follows:

$$\begin{aligned}
& \text{Context}_{15} = \text{if } (T_1 > T_2), \\
& \text{then } ((T_7 << 7) \mid (T_6 << 6) \mid (T_5 << 5) \mid (T_4 << 4) \mid (T_3 << 3) \mid (T_2 << 2) \mid \\
& \quad (T_1 << 1) \mid T_0); \\
& \text{else } ((T_5 << 7) \mid (T_4 << 6) \mid (T_7 << 5) \mid (T_6 << 4) \mid (T_3 << 3) \mid (T_1 << 2) \mid \\
& \quad (T_2 << 1) \mid T_0) \quad (17)
\end{aligned}$$

where “<<” is a left-shift operation and “|” is a bit wise logical OR operation, $T_7 = m^n_{(2i-1)(2j)}$, $T_6 = m^n_{(2i-1)(2j+1)}$, $T_5 = m^n_{(2i)(2j-1)}$, $T_4 = m^n_{(2i+1)(2j-1)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i)(j+1)}$, $T_1 = m^{n+1}_{(i+1)(j)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, $m^n_{(x)(y)}$ denotes the mask value at position (x,y) in spatial layer Λ_n , 2810. This context is identical to that of equation (9). It should be noted that the symmetric property is used to reduce the total possible context numbers to 192.

FIG. 29 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a binary context model for a second pixel $A(2i, 2j+1)$ 2912 in the third binary embodiment. Specifically, FIG. 29 illustrates the context construction, where the pixel 2912 with the question mark indicates the next pixel in the current spatial layer Λ_n 2910 whose mask value is to be encoded. Namely, FIG. 29 illustrates the construction of this context from both the lower spatial layer Λ_{n+1} 2900 and from a current spatial layer Λ_n 2910. The context number used by $A(2i, 2j+1)$ as shown in FIG. 29 can be given as follows:

$$\text{Context}_{16} = (T_6 << 6) \mid (T_5 << 5) \mid (T_4 << 4) \mid (T_3 << 3) \mid (T_2 << 2) \mid (T_1 << 1) \mid T_0 \quad (18)$$

where “<<” is a left-shift operation and “|” is a bit wise logical OR operation, $T_6 = m^n_{(2i)(2j)}$, $T_5 = m^n_{(2i-1)(2j)}$, $T_4 = m^n_{(2i-1)(2j+1)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i)(j+1)}$, $T_1 = m^{n+1}_{(i+1)(j)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, $m^n_{(x)(y)}$ denotes the mask value at position (x,y) in spatial layer Λ_n , 2910.

FIG. 30 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a binary context model for a third pixel $A(2i+1, 2j)$ 3012 in the third binary embodiment. Specifically, FIG. 30 illustrates the context construction, where the pixel 3012 with the question mark indicates the next pixel in the current spatial layer Λ_n 3010 whose mask value is to be encoded. Namely, FIG. 30

illustrates the construction of this context from both the lower spatial layer Λ_{n+1} 3000 and from a current spatial layer Λ_n 3010. The context number used by $A(2i+1, 2j)$ as shown in FIG. 30 can be given as follows:

$$\text{Context}_{17} = (T_6 \ll 6) \mid (T_5 \ll 5) \mid (T_4 \ll 4) \mid (T_3 \ll 3) \mid (T_2 \ll 2) \mid (T_1 \ll 1) \mid T_0 \quad (19)$$

where “ \ll ” is a left-shift operation and “ \mid ” is a bit wise logical OR operation, $T_6 = m^n_{(2i)(2j)}$, $T_5 = m^n_{(2i)(2j-1)}$, $T_4 = m^n_{(2i+1)(2j-1)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i+1)(j)}$, $T_1 = m^{n+1}_{(i)(j+1)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, $m^n_{(x)(y)}$ denotes the mask value at position (x,y) in spatial layer Λ_n , 3010. It should be noted that due to the symmetric property, $A(2i, 2j+1)$ and $A(2i+1, 2j)$ share the same context probability model but the formation of the contexts are different as shown in FIGs. 29 and 30.

FIG. 31 illustrates a block diagram of the relative positions of context elements for enhancement layer coding using a binary context model for a fourth pixel $A(2i+1, 2j+1)$ 2712 in the third binary embodiment. Specifically, FIG. 31 illustrates the context construction, where the pixel 3112 with the question mark indicates the next pixel in the current spatial layer Λ_n 3110 whose mask value is to be encoded. Namely, FIG. 31 illustrates the construction of this context from both the lower spatial layer Λ_{n+1} 3100 and from a current spatial layer Λ_n 3110. The context number used by $A(2i+1, 2j+1)$ as shown in FIG. 31 can be given as follows:

$$\begin{aligned} \text{Context}_{18} &= \text{if } (T_1 > T_2) \\ &\text{then } ((T_6 \ll 6) \mid (T_5 \ll 5) \mid (T_4 \ll 4) \mid (T_3 \ll 3) \mid (T_2 \ll 2) \mid (T_1 \ll 1) \mid T_0); \\ &\text{else } ((T_6 \ll 6) \mid (T_4 \ll 5) \mid (T_5 \ll 4) \mid (T_3 \ll 3) \mid (T_1 \ll 2) \mid (T_2 \ll 1) \mid T_0) \end{aligned} \quad (20)$$

where “ \ll ” is a left-shift operation and “ \mid ” is a bit wise logical OR operation, $T_6 = m^n_{(2i)(2j)}$, $T_5 = m^n_{(2i)(2j+1)}$, $T_4 = m^n_{(2i+1)(2j)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i)(j+1)}$, $T_1 = m^{n+1}_{(i+1)(j)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, $m^n_{(x)(y)}$ denotes the mask value at position (x,y) in spatial layer Λ_n , 3110. It should be noted that the symmetric property is used to reduce the total possible context numbers to 96.

The above binary arithmetic coding embodiments offer flexibility and provide backward compatibility. Namely, the block mode coding can

use the same VLC (Variable Length Coding) table as the binary shape coding method as described in MPEG-4 to provide full backward compatibility up to the base-layer. The base layer coding method uses the same coding scheme as the binary context-based arithmetic coding in the current version of the MPEG-4 standard, but without the block boundary (i.e. frame based coding). If no scalability function is required, then the base layer shape coding method resembles the binary context-based arithmetic coding with block boundary removed for frame based wavelet coding. Therefore the present coding method provides full backward compatibility with the current version of the MPEG-4 standard, while providing additional functionalities and higher coding efficiency

However, if the VLC table is used to code the block mode, the mode coding efficiency may not be as efficient as using the context-based arithmetic methods proposed in the present invention. Therefore, a single bit in the bitstream can be used to indicate to the decoder whether full-backward compatibility is chosen using VLC table to code the block mode or one of the context-based coding method is employed as described in the present invention. It should be noted that some degree of compatibility is still maintained even if context-based coding method is selected to gain the benefit of higher coding efficiency. Namely the binary context-based arithmetic encoder/decoder and the context used for mode coding and base layer coding are still the same as in the current version of the MPEG-4 standard.

Returning to FIG. 11, after step 1170 is completed, method 1100 returns to step 1165 and the loop formed by steps 1165 and 1170 is repeated until the highest mask layer is encoded.

The above description provides the encoding process of this spatially-scalable shape coder. However, it should be understood that a complementary as decoding process will follow the same steps except that after decoding the block mode, all blocks marked "ALL-0" will be filled with zeros (0's) and all blocks marked "ALL-1" will be filled with ones (1's) in order to form the correct context discussed above. An important aspect of the present invention is that the decoder can stop at any layer to retrieve the mask information for that spatial layer without receiving all the bits

for the full-resolution mask layer. Thus, the present invention provides a flexible spatial scalable shape encoding method and apparatus .

5 A second advantage is that different mask decomposition schemes will likely have different probabilities of distribution within each context, and the present scalable shape coder can be easily switched from one mask decomposition scheme to the other by changing the probability tables used by the arithmetic coder without changing the entire coding method.

10 Furthermore, it should be noted that in some cases, values of V^n may never appear within certain context for certain mask decomposition scheme. This can also be exploited to improve the coding efficiency. Namely, no bits will be spent to encode that pixel value, since it can be uniquely recovered from the context.

15 Although various embodiments which incorporate the teachings of the present invention have been shown and described in detail herein, those skilled in the art can readily devise many other varied embodiments that still incorporate these teachings.

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Appendix

Table A-I: The Probability Table For Class And Type In Block Mode
Coding

5

(a) Class

USInt Probclass[81]={

63791, 51557, 28328, 32768, 32768, 1, 51874, 32768, 4305, 32768, 32768, 32768,
52778, 32768, 65535, 38632, 32768, 32768, 48149, 32768, 1, 8606, 32768, 7842,
37282, 65535, 2146, 32768, 1, 65535, 32768, 32768, 32768, 32768, 32768,
32768, 61045, 20339, 1, 63788, 31086, 32768, 47382, 6997, 32768, 3408, 5705,
32768, 43931, 9039, 32768, 37682, 4999, 65505, 1111, 50158, 32768, 32768, 32768,
60396, 1, 14855, 32768, 65535, 18725, 1111, 63276, 33309, 1, 56969, 16602, 63411,
2601, 33559, 3569, 54228, 25358, 56719, 49771, 22819};

15

(b) Type

USInt Probtype[81]={

65282, 1, 54161, 32768, 32768, 32768, 65535, 32768, 50972, 32768, 32768, 32768,
1, 32768, 1, 1, 32768, 32768, 65535, 32768, 32768, 15124, 32768, 1, 61950, 1,
8738, 32768, 32768, 65535, 32768, 32768, 32768, 32768, 32768, 32768, 32768, 1, 1,
32768, 1, 1, 32768, 1, 1, 32768, 1170, 64674, 32768, 1, 1, 32768, 1, 30370, 65535,
65535, 65535, 32768, 32768, 32768, 65535, 32768, 65535, 32768, 1, 1, 65535, 1, 1,
32768, 1, 1, 65535, 1, 65150, 65535, 1, 511, 65535, 1, 25362};

25

662750 2622760

Table A-II: The Probability Table For Pixel T1 In Enhanced Layer Coding

(a) Odd Symmetric Filter

```

5  USInt scal_prob0_odd[256]={
    65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 25682, 29649, 83, 1096,
    28876, 19253, 2320, 292, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536,
    20597, 40071, 1, 1476, 6971, 9466, 4033, 314, 65536, 65536, 65536, 65536, 65536,
    65536, 65536, 65536, 34822, 58944, 1049, 888, 47296, 38677, 478, 14, 65536,
10  65536, 65536, 65536, 65536, 65536, 65536, 65536, 21384, 35003, 26, 7, 9600,
    13044, 44, 1, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 66, 13653,
    1, 1, 25105, 19008, 285, 31, 65536, 65536, 65536, 65536, 65536, 65536, 65536,
    65536, 1057, 27888, 1, 2521, 4252, 15367, 1, 751, 65536, 65536, 65536, 65536,
    65536, 65536, 65536, 65536, 290, 17476, 1, 1, 8625, 20056, 121, 3, 65536, 65536,
15  65536, 65536, 65536, 65536, 65536, 65536, 1960, 15984, 1, 1, 4747, 16480, 110, 9,
    65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 87, 140, 1, 55, 1205,
    1864, 1, 1, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 549, 2823, 1,
    1, 1902, 782, 1285, 130, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536,
    290, 6665, 1, 1, 15984, 8656, 1, 244, 65536, 65536, 65536, 65536, 65536, 65536,
20  65536, 65536, 63, 2114, 1, 3, 2138, 1560, 69, 1, 65536, 65536, 65536, 65536,
    65536, 65536, 65536, 65536, 1, 3178, 1, 218, 160, 66, 1, 2, 65536, 65536, 65536,
    65536, 65536, 65536, 65536, 65536, 35, 7047, 366, 180, 34, 113, 1, 9, 65536,
    65536, 65536, 65536, 65536, 65536, 65536, 65536, 837, 15124, 1, 1, 5571, 3236, 1,
    2, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 14, 1538, 1, 14, 31,
25  115, 1, 1};

```

(b) Even Symmetric Filter

```

USInt scal_prob0_even[256]={
5  65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 25542, 38525, 48333,
   53517, 26541, 23214, 61559, 59853, 65536, 65536, 65536, 65536, 65536, 65536,
   65536, 65536, 7151, 31006, 33480, 29879, 2609, 4142, 16384, 11884, 65536, 65536,
   65536, 65536, 65536, 65536, 65536, 65536, 44817, 65535, 56097, 64984, 40735,
   47710, 43386, 52046, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536,
  10  17545, 29626, 37308, 42263, 4196, 13552, 7199, 7230, 65536, 65536, 65536, 65536,
   65536, 65536, 65536, 65536, 1, 1, 1, 39322, 13578, 17416, 29218, 31831, 65536,
   65536, 65536, 65536, 65536, 65536, 65536, 65536, 1311, 65535, 32768, 7282, 1,
   3048, 25206, 19935, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 1,
   32768, 17873, 61861, 3417, 14895, 4541, 5293, 65536, 65536, 65536, 65536, 65536,
   65536, 65536, 65536, 4819, 32768, 39950, 43523, 1148, 4021, 12072, 5436, 65536,
  15  65536, 65536, 65536, 65536, 65536, 65536, 65536, 1, 1, 134, 1, 1, 55, 5461, 2849,
   65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 24, 5243, 590, 1079, 86,
   95, 14564, 7159, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 328, 1,
   2564, 14919, 21845, 1, 9362, 15880, 65536, 65536, 65536, 65536, 65536, 65536,
   65536, 65536, 43, 362, 150, 1179, 752, 529, 683, 331, 65536, 65536, 65536, 65536,
  20  65536, 65536, 65536, 65536, 1, 1, 700, 862, 25, 24, 1317, 558, 65536, 65536,
   65536, 65536, 65536, 65536, 65536, 65536, 1, 1, 1, 172, 2, 4, 793, 342, 65536,
   65536, 65536, 65536, 65536, 65536, 65536, 65536, 572, 1, 1928, 43080, 3337, 1680,
   1401, 2131, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 18, 1, 366,
   7456, 8, 18, 40, 8};

```

Table A-III: The Probability Table For Pixel T0 In Enhanced Layer Coding

(a) Odd Symmetric Filter

```

5  USInt scal_prob1_odd[256]={
    65536, 65536, 54236, 62309, 65536, 65536, 39146, 32459, 0, 0, 0, 0, 0, 0, 0, 0,
    65536, 65536, 3293, 20806, 65536, 65536, 20132, 22080, 0, 0, 0, 0, 0, 0, 0, 0,
    65536, 65536, 62837, 40750, 65536, 65536, 36528, 20960, 0, 0, 0, 0, 0, 0, 0, 0,
    65536, 65536, 46875, 21025, 65536, 65536, 35747, 30778, 0, 0, 0, 0, 0, 0, 0, 0,
10  65536, 65536, 63956, 52735, 65536, 65536, 32974, 6233, 0, 0, 0, 0, 0, 0, 0, 0,
    65536, 65536, 39449, 40885, 65536, 65536, 23406, 10898, 0, 0, 0, 0, 0, 0, 0, 0,
    65536, 65536, 62156, 12655, 65536, 65536, 23973, 3451, 0, 0, 0, 0, 0, 0, 0, 0,
    65536, 65536, 31892, 3756, 65536, 65536, 24045, 14281, 0, 0, 0, 0, 0, 0, 0, 0,
    65537, 65537, 65537, 65537, 65537, 65537, 65537, 65537, 51966, 33057, 1, 6782,
15  62238, 32046, 5919, 418, 65537, 65537, 65537, 65537, 65537, 65537, 65537, 65537,
    64435, 18941, 1224, 7203, 52134, 4674, 6753, 1113, 65537, 65537, 65537, 65537,
    65537, 65537, 65537, 65537, 62703, 34133, 16705, 28007, 31477, 15453, 21558,
    6073, 65537, 65537, 65537, 65537, 65537, 65537, 65537, 65537, 65537, 61951, 29954,
    4826, 6481, 12288, 2410, 4466, 228, 65537, 65537, 65537, 65537, 65537, 65537,
20  65537, 65537, 1789, 23069, 726, 7470, 30386, 26721, 9811, 1446, 65537, 65537,
    65537, 65537, 65537, 65537, 65537, 65537, 45333, 28672, 21363, 26870, 41125,
    9455, 25752, 12372, 65537, 65537, 65537, 65537, 65537, 65537, 65537, 65537,
    46324, 37071, 4994, 5136, 18879, 28687, 9330, 366, 65537, 65537, 65537, 65537,
    65537, 65537, 65537, 65537, 31745, 26116, 346, 397, 2900, 13830, 361, 8};

```

25

(b) Even Symmetric Filter

USInt scal_prob1_even[256]={

5 65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 0, 0, 0, 0, 0, 0, 0, 0,

65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 0, 0, 0, 0, 0, 0, 0, 0,

65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 0, 0, 0, 0, 0, 0, 0, 0,

65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 0, 0, 0, 0, 0, 0, 0, 0,

65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 0, 0, 0, 0, 0, 0, 0, 0,

10 65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 0, 0, 0, 0, 0, 0, 0, 0,

65536, 65536, 65536, 65536, 65536, 65536, 65536, 65536, 0, 0, 0, 0, 0, 0, 0, 0,

65537, 65537, 65537, 65537, 65537, 65537, 65537, 65537, 54018, 8704, 1, 903,

61648, 31196, 327, 575, 65537, 65537, 65537, 65537, 65537, 65537, 65537, 65537,

64400, 36956, 1673, 9758, 52289, 4361, 659, 1433, 65537, 65537, 65537, 65537,

15 65537, 65537, 65537, 65537, 56482, 65535, 1, 1, 11905, 3034, 1, 1, 65537, 65537,

65537, 65537, 65537, 65537, 65537, 65537, 61103, 56650, 925, 8814, 11845, 2075,

828, 223, 65537, 65537, 65537, 65537, 65537, 65537, 65537, 65537, 4161, 1, 494,

5041, 52508, 32195, 11005, 2463, 65537, 65537, 65537, 65537, 65537, 65537,

65537, 65537, 63286, 32768, 39133, 49486, 53351, 8541, 37603, 15011, 65537,

20 65537, 65537, 65537, 65537, 65537, 65537, 65537, 18805, 13107, 1039, 1214, 5060,

21845, 3830, 387, 65537, 65537, 65537, 65537, 65537, 65537, 65537, 65537, 31654,

32951, 490, 1496, 2535, 11699, 328, 13};

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What is claimed is:

1. A method for coding an input object mask, where said input object mask has a plurality of regions, said method comprising the steps of:

- 5 (a) assigning at least one symbol to each of the plurality of regions;
 (b) coding said assigned symbols of the input object mask;
 (c) decomposing said input object mask into a plurality of object mask layers;

10 (d) coding a base object layer of said plurality of object mask layers;
 and

(e) coding a next higher layer of said plurality of object mask layers in accordance with information from a lower object mask layer.

15 2. The method of claim 1, wherein said coding step (b) codes said assigned symbols contextually in accordance with neighboring regions.

3. The method of claim 2, wherein said coding step (b) codes said assigned symbols contextually in accordance with:

20
$$context_0 = S_3 * 27 + S_2 * 9 + S_1 * 3 + S_0,$$

where $context_0$ is a context for an assigned symbol for a current region, M_{ij} , to be coded, i and j are respectively row index and column index, and wherein said neighboring regions are defined as $S_3 = M_{(i-1)(j-1)}$, $S_2 = M_{(i-1)j}$,

25 $S_1 = M_{(i-1)(j+1)}$, and $S_0 = M_{ij-1}$.

4. The method of claim 1, wherein said coding step (b) codes said assigned symbols contextually using binary context-based arithmetic coding.

30

5. The method of claim 4, wherein said coding step (b) codes said assigned symbols contextually using binary context-based arithmetic coding having two classes.

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6. The method of claim 1, wherein said coding step (d) codes mask values of said base object layer contextually in accordance with neighboring regions.

- 5 7. The method of claim 6, wherein said coding step (d) codes said mask values of said base object layer contextually in accordance with:

$$\text{context}_1 = (C_9 \ll 9) \mid (C_8 \ll 8) \mid (C_7 \ll 7) \mid (C_6 \ll 6) \mid (C_5 \ll 5) \mid (C_4 \ll 4) \mid (C_3 \ll 3) \mid (C_2 \ll 2) \mid (C_1 \ll 1) \mid C_0,$$

10

where “ \ll ” is a left-shift operation, “ \mid ” is a bit wise logical OR operation, context_1 is a context for a current base-layer mask value (m_{ij}^L) to be coded, i and j are respectively row index and column index, and wherein said neighboring regions are defined as $C_9 = m_{(i-2)(j-1)}^L$, $C_8 = m_{(i-2)j}^L$, $C_7 = m_{(i-2)(j+1)}^L$, $C_6 = m_{(i-1)(j-2)}^L$, $C_5 = m_{(i-1)(j-1)}^L$, $C_4 = m_{(i-1)j}^L$, $C_3 = m_{(i-1)(j+1)}^L$, $C_2 = m_{(i-1)(j+2)}^L$, $C_1 = m_{ij-2}^L$, and $C_0 = m_{ij-1}^L$.

15

8. The method of claim 1, wherein said coding step (e) codes a region, V^n , within said next higher layer of said plurality of object mask layers, wherein said region is represented as:

20

$$V^n = m_{(2i)(2j)}^n * 8 + m_{(2i)(2j+1)}^n * 4 + m_{(2i+1)(2j)}^n * 2 + m_{(2i+1)(2j+1)}^n$$

where i and j are row and column indices of said region, V^n , corresponding to in a previous lower spatial object layer.

25

9. The method of claim 1, wherein said coding step (e) codes a current region within said next higher layer of said plurality of object mask layers contextually in accordance with:

30

$$\text{context}_2 = (T_7 \ll 7) \mid (T_6 \ll 6) \mid (T_5 \ll 5) \mid (T_4 \ll 4) \mid (T_3 \ll 3) \mid (T_2 \ll 2) \mid (T_1 \ll 1) \mid (T_0),$$

where “<<” is a left-shift operation and “|” is a bit wise logical OR operation, context_2 is a context for said current region within said next higher layer to be coded, i and j are respectively row index and column index, $T_7 = m^{n+1}_{(2i-1)(2j)}$, $T_6 = m^n_{(2i-1)(2j+1)}$, $T_5 = m^n_{(2i)(2j-1)}$, $T_4 = m^n_{(2i+1)(2j-1)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i)(j+1)}$, $T_1 = m^{n+1}_{(i+1)(j)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, and $m^n_{(x)(y)}$ denotes the mask value at position (x,y) in a lower spatial object layer.

10. The method of claim 1, wherein said coding step (e) codes a current region within said next higher layer of said plurality of object mask layers contextually in two-passes using a half-higher spatial layer.

11. The method of claim 10, wherein said coding step (e) codes in a first pass said current region having a plurality of pixels, wherein at least one of said plurality of pixels is coded contextually in accordance with:

$$\text{Context}_3 = (T_9 < < 7) | (T_8 < < 6) | (T_7 < < 5) | (T_6 < < 4) | (T_5 < < 3) | (T_4 < < 2) | (T_3 < < 1) | (T_2),$$

where “<<” is a left-shift operation and “|” is a bit wise logical OR operation, context_3 is a context for said at least one pixel to be coded, i and j are respectively row index and column index, $T_9 = m^{n+1/2}_{(2i-1)(j)}$, $T_8 = m^{n+1/2}_{(2i-1)(j+1)}$, $T_7 = m^{n+1/2}_{(2i+1)(j-1)}$, $T_6 = m^{n+1/2}_{(2i)(j-1)}$, $T_5 = m^{n+1}_{(i)(j)}$, $T_4 = m^{n+1}_{(i)(j+1)}$, $T_3 = m^{n+1}_{(i+1)(j)}$, $T_2 = m^{n+1}_{(i+1)(j+1)}$, where T_6 through T_9 correspond to pixels in said half-higher spatial object layer, and T_5 through T_2 and T_{10} correspond to pixels in a lower spatial object layer.

12. The method of claim 10, wherein said coding step (e) codes in a first pass said current region having a plurality of pixels, wherein at least one of said plurality of pixels is coded contextually in accordance with:

$$\text{Context}_4 = (T_1 < < 7) | (T_{10} < < 6) | (T_7 < < 5) | (T_6 < < 4) | (T_5 < < 3) | (T_4 < < 2) | (T_3 < < 1) | (T_2),$$

where “<<” is a left-shift operation and “|” is a bit wise logical OR operation, context_4 is a context for said at least one pixel to be coded, i and j are respectively row index and column index, $T_7 = m^{n+1/2}_{(2i+1)(j-1)}$, $T_6 = m^{n+1/2}_{(2i)(j-1)}$, $T_5 = m^{n+1}_{(i)(j)}$, $T_4 = m^{n+1}_{(i)(j+1)}$, $T_3 = m^{n+1}_{(i+1)(j)}$, $T_2 = m^{n+1}_{(i+1)(j+1)}$, $T_{10} = m^{n+1}_{(i+1)(j-1)}$, $T_1 = m^{n+1/2}_{(2i)(j)}$, $T_0 = m^{n+1/2}_{(2i+1)(j)}$, where T_6 through T_7 and T_1 correspond to pixels in said half-higher spatial object layer, and T_5 through T_2 and T_{10} correspond to pixels in a lower spatial object layer.

13. The method of claim 10, wherein said coding step (e) codes in a second pass said current region having a plurality of pixels, wherein at least one of said plurality of pixels is coded contextually in accordance with:

$$\text{Context}_5 = (T_9 \ll 7) | (T_8 \ll 6) | (T_7 \ll 5) | (T_6 \ll 4) | (T_5 \ll 3) | (T_4 \ll 2) | (T_3 \ll 1) | (T_2),$$

- where “<<” is a left-shift operation and “|” is a bit wise logical OR operation, context_5 is a context for said at least one pixel to be coded, i and j are respectively row index and column index, $T_9 = m^n_{(i)(2j-1)}$, $T_8 = m^n_{(i+1)(2j-1)}$, $T_7 = m^n_{(i-1)(2j+1)}$, $T_6 = m^n_{(i-1)(2j)}$, $T_5 = m^{n+1/2}_{(i)(j)}$, $T_4 = m^{n+1/2}_{(i+1)(j)}$, $T_3 = m^{n+1/2}_{(i)(j+1)}$, $T_2 = m^{n+1/2}_{(i+1)(j+1)}$, and where T_6 through T_9 correspond to pixels in a current higher object layer and T_5 through T_2 , correspond to pixels in a lower spatial object layer.

14. The method of claim 10, wherein said coding step (e) codes in a second pass said current region having a plurality of pixels, wherein at least one of said plurality of pixels is coded contextually in accordance with:

$$\text{Context}_6 = (T_1 \ll 7) | (T_{10} \ll 6) | (T_7 \ll 5) | (T_6 \ll 4) | (T_5 \ll 3) | (T_4 \ll 2) | (T_3 \ll 1) | (T_2),$$

where “<<” is a left-shift operation and “|” is a bit wise logical OR operation, context_6 is a context for said at least one pixel to be coded, i and j

are respectively row index and column index, $T_7 = m^n_{(i-1)(2j+1)}$, $T_6 = m^n_{(i-1)(2j)}$, $T_5 = m^{n+1/2}_{(i)(j)}$, $T_4 = m^{n+1/2}_{(i+1)(j)}$, $T_3 = m^{n+1/2}_{(i)(j+1)}$, $T_2 = m^{n+1/2}_{(i+1)(j+1)}$, $T_{10} = m^{n+1/2}_{(i-1)(j+1)}$, $T_1 = m^n_{(i)(2j)}$, and where T_6 through T_7 and T_1 correspond to pixels in a current higher object layer and T_5 through T_2 , and T_{10} correspond to pixels in a lower spatial object layer.

15. The method of claim 1, wherein said coding step (e) codes a current region within said next higher layer of said plurality of object mask layers contextually using binary context-based arithmetic coding.

16. The method of claim 15, wherein said current region has a plurality of pixels, and wherein said coding step (e) codes at least one of said plurality of pixels of said current region within said next higher layer of said plurality of object mask layers contextually in accordance with:

$$\text{Context}_7 = (T_7 << 7) \mid (T_6 << 6) \mid (T_5 << 5) \mid (T_4 << 4) \mid (T_3 << 3) \mid (T_2 << 2) \mid (T_1 << 1) \mid T_0,$$

where "<<" is a left-shift operation and "|" is a bit wise logical OR operation, context_7 is a context for said at least one pixel to be coded, i and j are respectively row index and column index, $T_7 = m^n_{(2i-1)(2j)}$, $T_6 = m^n_{(2i-1)(2j+1)}$, $T_5 = m^n_{(2i)(2j-1)}$, $T_4 = m^n_{(2i+1)(2j-1)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i)(j+1)}$, $T_1 = m^{n+1}_{(i+1)(j)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, and where T_7 through T_4 correspond to pixels in a current higher object layer and T_3 through T_0 correspond to pixels in a lower spatial object layer.

17. The method of claim 15, wherein said current region has a plurality of pixels, and wherein said coding step (e) codes at least one of said plurality of pixels of said current region within said next higher layer of said plurality of object mask layers contextually in accordance with:

$$\text{Context}_8 = (T_8 << 8) \mid (T_7 << 7) \mid (T_6 << 6) \mid (T_5 << 5) \mid (T_4 << 4) \mid (T_3 << 3) \mid (T_2 << 2) \mid (T_1 << 1) \mid T_0,$$

where “<<” is a left-shift operation and “|” is a bit wise logical OR operation, context₈ is a context for said at least one pixel to be coded, i and j are respectively row index and column index, $T_8 = m^n_{(2i)(2j)}$, $T_7 = m^n_{(2i-1)(2j)}$, $T_6 = m^n_{(2i-1)(2j+1)}$, $T_5 = m^n_{(2i)(2j-1)}$, $T_4 = m^n_{(2i+1)(2j-1)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i)(j+1)}$, $T_1 = m^{n+1}_{(i+1)(j)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, and where T_8 through T_4 correspond to pixels in a current higher object layer and T_3 through T_0 correspond to pixels in a lower spatial object layer.

18. The method of claim 15, wherein said current region has a plurality of pixels, and wherein said coding step (e) codes at least one of said plurality of pixels of said current region within said next higher layer of said plurality of object mask layers contextually in accordance with:

$$\text{Context}_9 = (T_9 << 9) \mid (T_8 << 8) \mid (T_7 << 7) \mid (T_6 << 6) \mid (T_5 << 5) \mid (T_4 << 4) \mid (T_3 << 3) \mid (T_2 << 2) \mid (T_1 << 1) \mid T_0,$$

where “<<” is a left-shift operation and “|” is a bit wise logical OR operation, context₉ is a context for said at least one pixel to be coded, i and j are respectively row index and column index, $T_9 = m^n_{(2i)(2j+1)}$, $T_8 = m^n_{(2i)(2j)}$, $T_7 = m^n_{(2i-1)(2j)}$, $T_6 = m^n_{(2i-1)(2j+1)}$, $T_5 = m^n_{(2i)(2j-1)}$, $T_4 = m^n_{(2i+1)(2j-1)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i)(j+1)}$, $T_1 = m^{n+1}_{(i+1)(j)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, and where T_9 through T_4 correspond to pixels in a current higher object layer and T_3 through T_0 correspond to pixels in a lower spatial object layer.

19. The method of claim 15, wherein said current region has a plurality of pixels, and wherein said coding step (e) codes at least one of said plurality of pixels of said current region within said next higher layer of said plurality of object mask layers contextually in accordance with:

$$\text{Context}_{10} = (T_{10} << 10) \mid (T_9 << 9) \mid (T_8 << 8) \mid (T_7 << 7) \mid (T_6 << 6) \mid (T_5 << 5) \mid (T_4 << 4) \mid (T_3 << 3) \mid (T_2 << 2) \mid (T_1 << 1) \mid T_0,$$

where “<<” is a left-shift operation and “|” is a bit wise logical OR operation, context₁₀ is a context for said at least one pixel to be coded, i and

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j are respectively row index and column index, , $T_{10}=m^n_{(2i+1)(2j)}$, $T_9=m^n_{(2i)(2j+1)}$, $T_8=m^n_{(2i)(2j)}$, $T_7=m^n_{(2i-1)(2j)}$, $T_6=m^n_{(2i-1)(2j+1)}$, $T_5=m^n_{(2i)(2j-1)}$, $T_4=m^n_{(2i+1)(2j-1)}$, $T_3=m^{n+1}_{(i)(j)}$, $T_2=m^{n+1}_{(i)(j+1)}$, $T_1=m^{n+1}_{(i+1)(j)}$, $T_0=m^{n+1}_{(i+1)(j+1)}$, and where T_{10} through T_4 correspond to pixels in a current higher object layer and T_3 through T_0 correspond to pixels in a lower spatial object layer.

20. The method of claim 15, wherein said current region has a plurality of pixels, and wherein said coding step (e) codes at least one of said plurality of pixels of said current region within said next higher layer of said plurality of object mask layers contextually in accordance with:

$$\text{Context}_{12} = (T_6 \ll 6) \mid (T_5 \ll 5) \mid (T_4 \ll 4) \mid (T_3 \ll 3) \mid (T_2 \ll 2) \mid (T_1 \ll 1) \mid T_0,$$

where “ \ll ” is a left-shift operation and “ \mid ” is a bit wise logical OR operation, context_{12} is a context for said at least one pixel to be coded, i and j are respectively row index and column index, $T_6=m^n_{(2i)(2j)}$, $T_5=m^n_{(2i-1)(2j)}$, $T_4=m^n_{(2i-1)(2j+1)}$, $T_3=m^{n+1}_{(i)(j)}$, $T_2=m^{n+1}_{(i)(j+1)}$, $T_1=m^{n+1}_{(i+1)(j)}$, $T_0=m^{n+1}_{(i+1)(j+1)}$, and where T_6 through T_4 correspond to pixels in a current higher object layer and T_3 through T_0 correspond to pixels in a lower spatial object layer.

21. The method of claim 15, wherein said current region has a plurality of pixels, and wherein said coding step (e) codes at least one of said plurality of pixels of said current region within said next higher layer of said plurality of object mask layers contextually in accordance with:

$$\text{Context}_{13} = (T_7 \ll 7) \mid (T_6 \ll 6) \mid (T_5 \ll 5) \mid (T_4 \ll 4) \mid (T_3 \ll 3) \mid (T_2 \ll 2) \mid (T_1 \ll 1) \mid T_0,$$

where “ \ll ” is a left-shift operation and “ \mid ” is a bit wise logical OR operation, context_{13} is a context for said at least one pixel to be coded, i and j are respectively row index and column index, $T_7=m^n_{(2i)(2j)}$, $T_6=m^n_{(2i)(2j+1)}$, $T_5=m^n_{(2i)(2j-1)}$, $T_4=m^n_{(2i+1)(2j-1)}$, $T_3=m^{n+1}_{(i)(j)}$, $T_2=m^{n+1}_{(i)(j+1)}$, $T_1=m^{n+1}_{(i+1)(j)}$, $T_0=m^{n+1}_{(i+1)(j+1)}$, and where T_7 through T_4 correspond to pixels in a current

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higher object layer and T_3 through T_0 correspond to pixels in a lower spatial object layer.

22. The method of claim 15, wherein said current region has a plurality of pixels, and wherein said coding step (e) codes at least one of said plurality of pixels of said current region within said next higher layer of said plurality of object mask layers contextually in accordance with:

$$\text{Context}_{14} = (T_6 << 6) \mid (T_5 << 5) \mid (T_4 << 4) \mid (T_3 << 3) \mid (T_2 << 2) \mid (T_1 << 1) \mid T_0,$$

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where “<<” is a left-shift operation and “|” is a bit wise logical OR operation, context_{14} is a context for said at least one pixel to be coded, i and j are respectively row index and column index, $T_6 = m^n_{(2i)(2j)}$, $T_5 = m^n_{(2i)(2j+1)}$, $T_4 = m^n_{(2i+1)(2j)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i)(j+1)}$, $T_1 = m^{n+1}_{(i+1)(j)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, and where T_6 through T_4 correspond to pixels in a current higher object layer and T_3 through T_0 correspond to pixels in a lower spatial object layer.

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23. The method of claim 15, wherein said current region has a plurality of pixels, and wherein said coding step (e) codes at least one of said plurality of pixels of said current region within said next higher layer of said plurality of object mask layers contextually in accordance with:

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$$\begin{aligned} \text{Context}_{15} &= \text{if } (T_1 > T_2), \\ &\text{then } ((T_7 << 7) \mid (T_6 << 6) \mid (T_5 << 5) \mid (T_4 << 4) \mid (T_3 << 3) \mid (T_2 << 2) \\ &\quad \mid (T_1 << 1) \mid T_0); \\ &\text{else } ((T_5 << 7) \mid (T_4 << 6) \mid (T_7 << 5) \mid (T_6 << 4) \mid (T_3 << 3) \mid (T_1 << 2) \mid (T_2 \\ &\quad << 1) \mid T_0), \end{aligned}$$

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- where “<<” is a left-shift operation and “|” is a bit wise logical OR operation, context_{15} is a context for said at least one pixel to be coded, i and j are respectively row index and column index, $T_7 = m^n_{(2i-1)(2j)}$, $T_6 = m^n_{(2i-1)(2j+1)}$, $T_5 = m^n_{(2i)(2j-1)}$, $T_4 = m^n_{(2i+1)(2j-1)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i)(j+1)}$, $T_1 = m^{n+1}_{(i+1)(j)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, and where T_7 through T_4 correspond to pixels in a current

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higher object layer and T_3 through T_0 correspond to pixels in a lower spatial object layer.

24. The method of claim 15, wherein said current region has a plurality of pixels, and wherein said coding step (e) codes at least one of said plurality of pixels of said current region within said next higher layer of said plurality of object mask layers contextually in accordance with:

$$\text{Context}_{16} = (T_6 \ll 6) \mid (T_5 \ll 5) \mid (T_4 \ll 4) \mid (T_3 \ll 3) \mid (T_2 \ll 2) \mid (T_1 \ll 1) \mid T_0,$$

- where “ \ll ” is a left-shift operation and “ \mid ” is a bit wise logical OR operation, context_{16} is a context for said at least one pixel to be coded, i and j are respectively row index and column index, $T_6 = m^n_{(2i)(2j)}$, $T_5 = m^n_{(2i-1)(2j)}$, $T_4 = m^n_{(2i-1)(2j+1)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i)(j+1)}$, $T_1 = m^{n+1}_{(i+1)(j)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, and where T_6 through T_4 correspond to pixels in a current higher object layer and T_3 through T_0 correspond to pixels in a lower spatial object layer.

25. The method of claim 15, wherein said current region has a plurality of pixels, and wherein said coding step (e) codes at least one of said plurality of pixels of said current region within said next higher layer of said plurality of object mask layers contextually in accordance with:

$$\text{Context}_{17} = (T_6 \ll 6) \mid (T_5 \ll 5) \mid (T_4 \ll 4) \mid (T_3 \ll 3) \mid (T_2 \ll 2) \mid (T_1 \ll 1) \mid T_0,$$

- where “ \ll ” is a left-shift operation and “ \mid ” is a bit wise logical OR operation, context_{17} is a context for said at least one pixel to be coded, i and j are respectively row index and column index, $T_6 = m^n_{(2i)(2j)}$, $T_5 = m^n_{(2i)(2j-1)}$, $T_4 = m^n_{(2i+1)(2j-1)}$, $T_3 = m^{n+1}_{(i)(j)}$, $T_2 = m^{n+1}_{(i+1)(j)}$, $T_1 = m^{n+1}_{(i)(j+1)}$, $T_0 = m^{n+1}_{(i+1)(j+1)}$, and where T_6 through T_4 correspond to pixels in a current higher object layer and T_3 through T_0 correspond to pixels in a lower spatial object layer.

26. The method of claim 15, wherein said current region has a plurality of pixels, and wherein said coding step (e) codes at least one of said plurality of pixels of said current region within said next higher layer of said plurality of object mask layers contextually in accordance with:

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Context₁₈ = if (T₁>T₂)
 then ((T₆<<6) | (T₅<<5) | (T₄<<4) | (T₃<<3) | (T₂<<2) | (T₁<<1) | T₀);
 else ((T₆<<6) | (T₄<<5) | (T₅<<4) | (T₃<<3) | (T₁<<2) | (T₂<<1) | T₀),

10 where "<<" is a left-shift operation and "|" is a bit wise logical OR operation, context₁₈ is a context for said at least one pixel to be coded, i and j are respectively row index and column index, T₆=mⁿ_{(2i)(2j)}, T₅=mⁿ_{(2i)(2j+1)}, T₄=mⁿ_{(2i+1)(2j)}, T₃=mⁿ⁺¹_{(i)(j)}, T₂=mⁿ⁺¹_{(i)(j+1)}, T₁=mⁿ⁺¹_{(i+1)(j)}, T₀=mⁿ⁺¹_{(i+1)(j+1)}, and where T₆ through T₄ correspond to pixels in a current higher object layer
 15 and T₃ through T₀ correspond to pixels in a lower spatial object layer.

27. A computer-readable medium having stored thereon a plurality of instructions, the plurality of instructions including instructions which, when executed by a processor, cause the processor to perform the steps comprising of:

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- (a) assigning at least one symbol to each of the plurality of regions;
- (b) coding said assigned symbols of the input object mask;
- (c) decomposing said input object mask into a plurality of object mask layers;
- 25 (d) coding a base object layer of said plurality of object mask layers; and
- (e) coding a next higher layer of said plurality of object mask layers in accordance with information from a lower object mask layer.

30 28. The computer-readable medium of claim 27, wherein said coding step (b) codes said assigned symbols contextually in accordance with neighboring regions.

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29. An apparatus for coding an input object mask, where said input object mask has a plurality of regions, said method comprising the steps of:

- 5 means for assigning at least one symbol to each of the plurality of regions;
- a first means for coding said assigned symbols of the input object mask;
- means for decomposing said input object mask into a plurality of object mask layers;
- 10 a second means for coding a base object layer of said plurality of object mask layers; and
- a third means for coding a next higher layer of said plurality of object mask layers in accordance with information from a lower object mask layer.

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30. The apparatus of claim 29, wherein said first coding means codes said assigned symbols contextually in accordance with neighboring regions.

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ABSTRACT

A generic spatially-scalable shape encoding apparatus and method for handling different mask decomposition methods, while maximizing coding efficiency of the encoder, is disclosed. The present generic
5 spatially-scalable shape encoding applies three encoding steps to maximize the coding efficiency of the encoder, i.e., mask mode encoding, base mask layer coding and enhancement mask layer coding.

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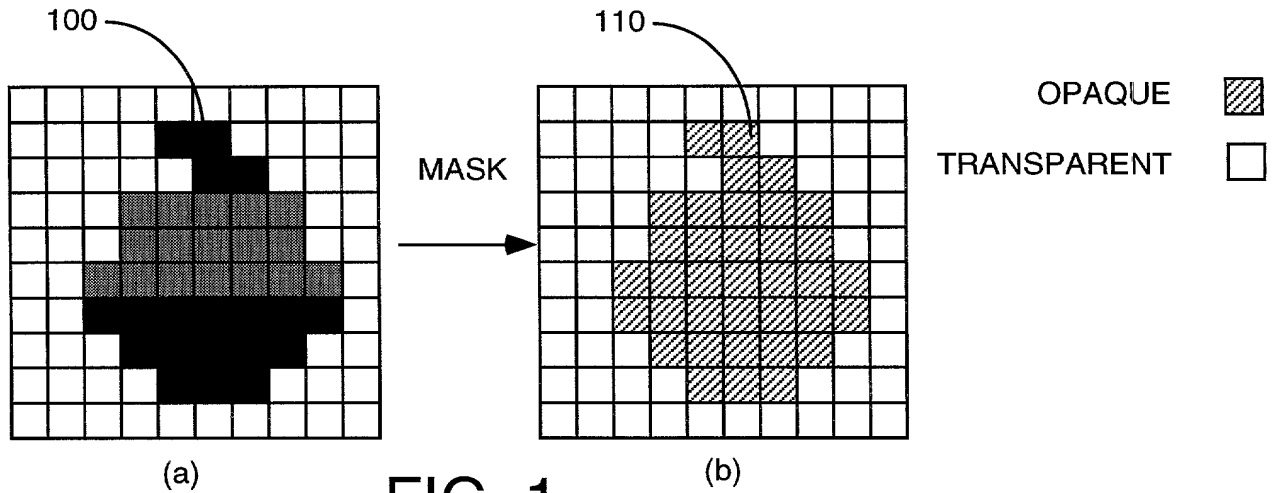


FIG. 1

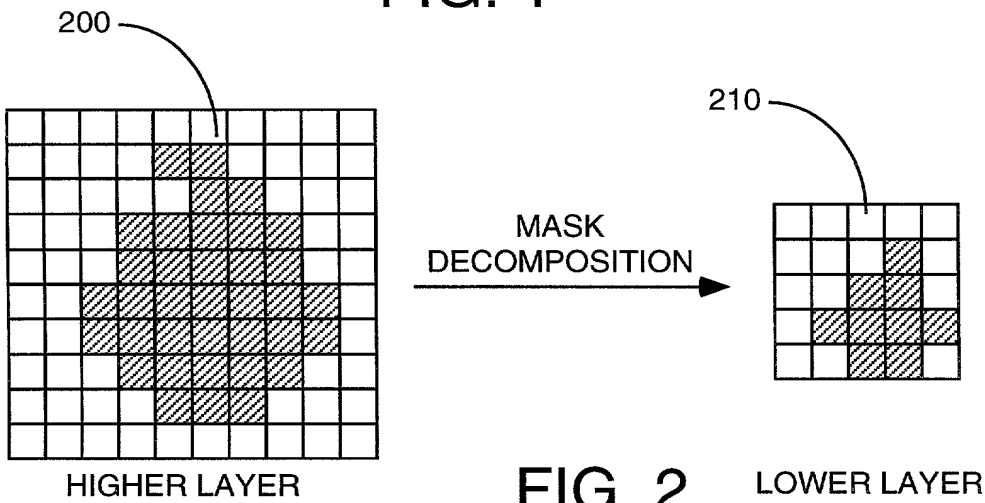


FIG. 2

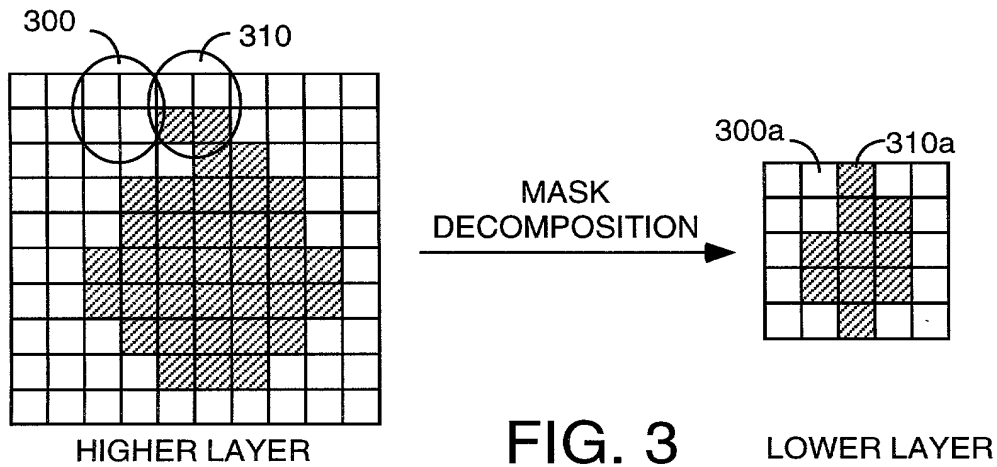
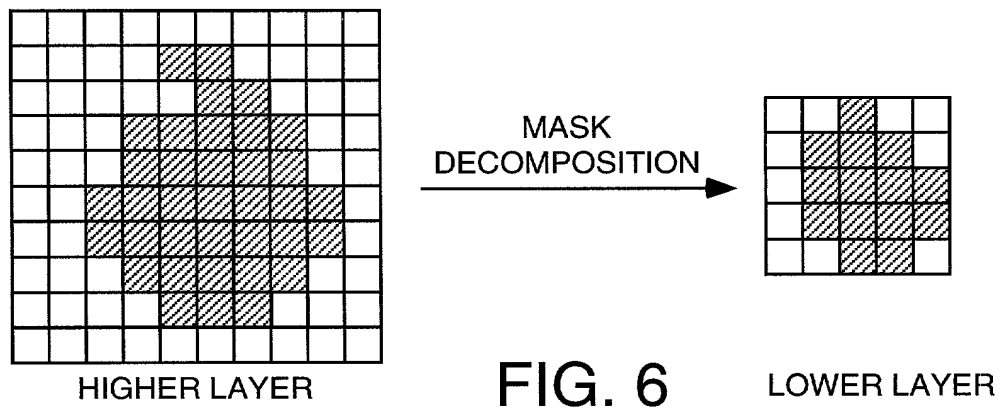
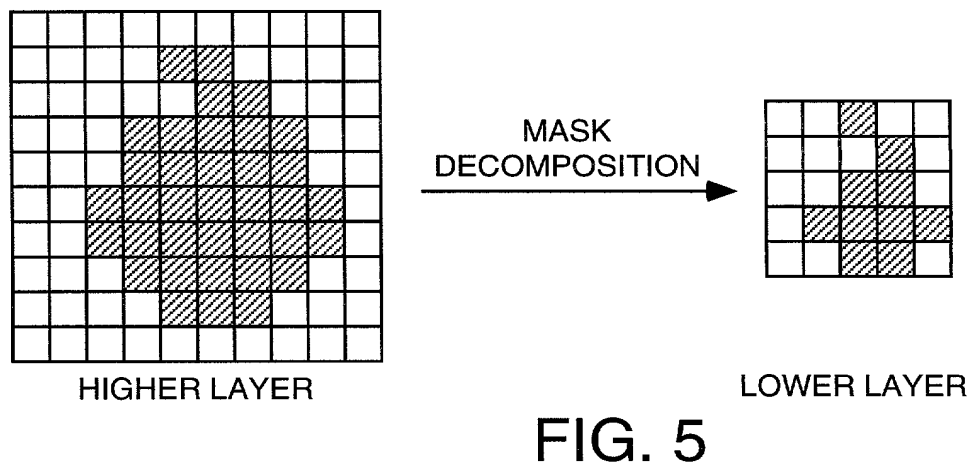
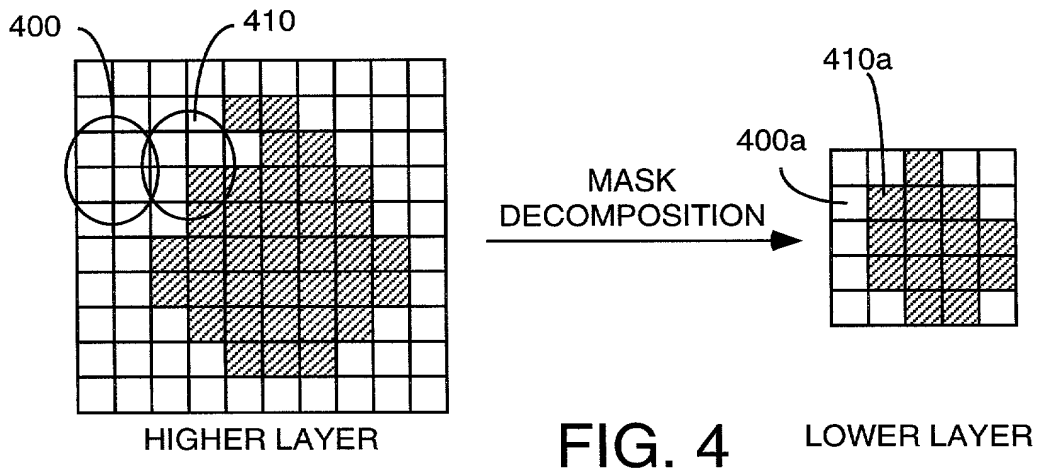


FIG. 3



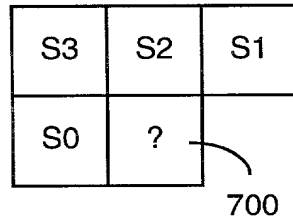


FIG. 7

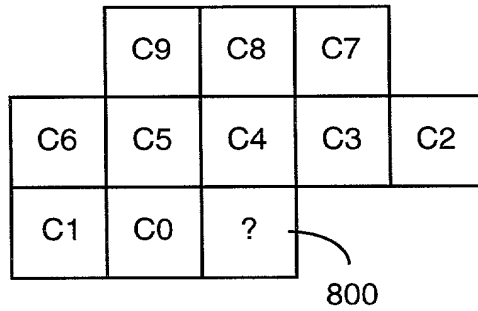


FIG. 8

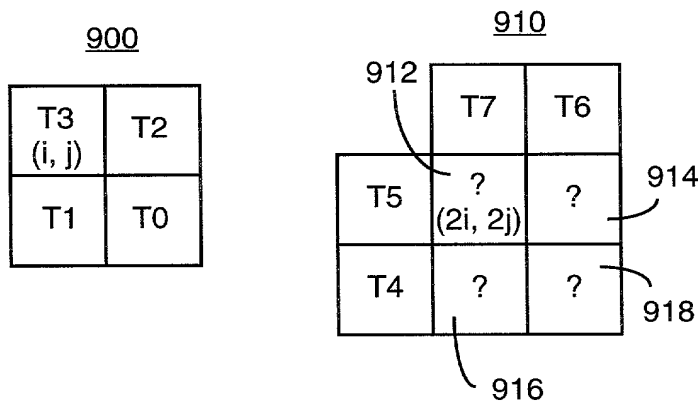


FIG. 9

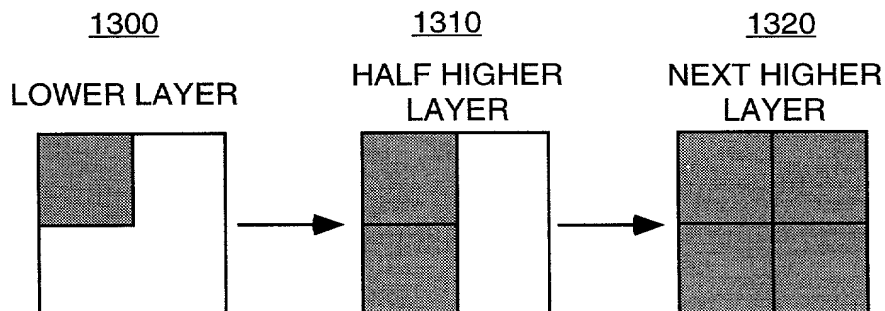


FIG. 13

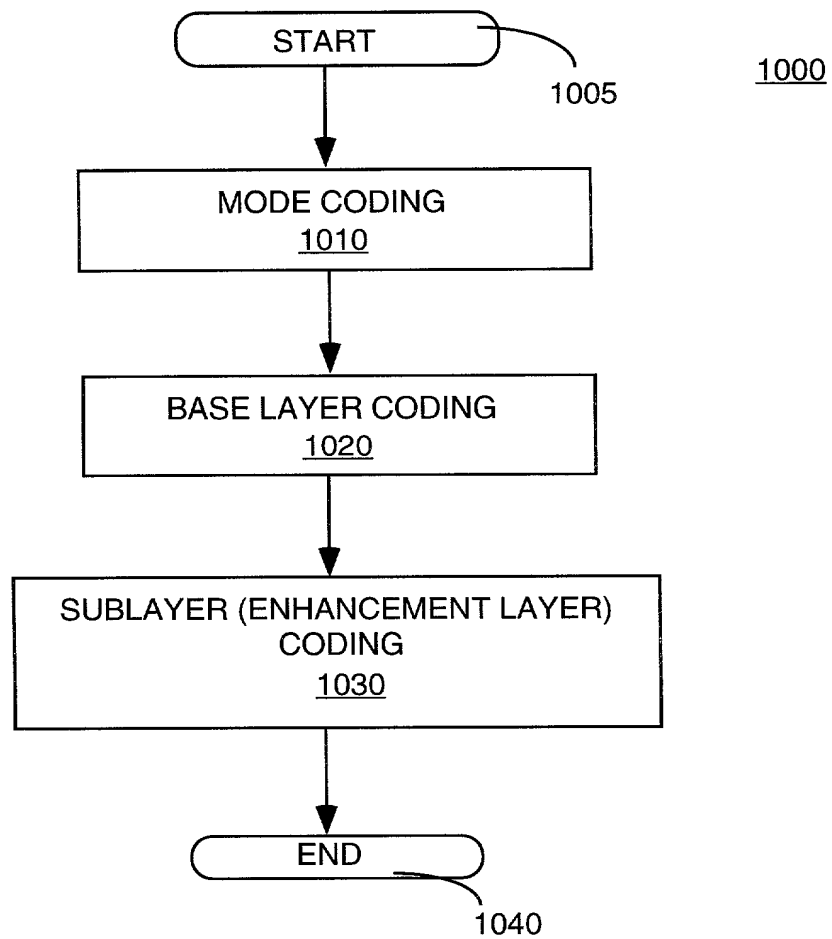


FIG. 10

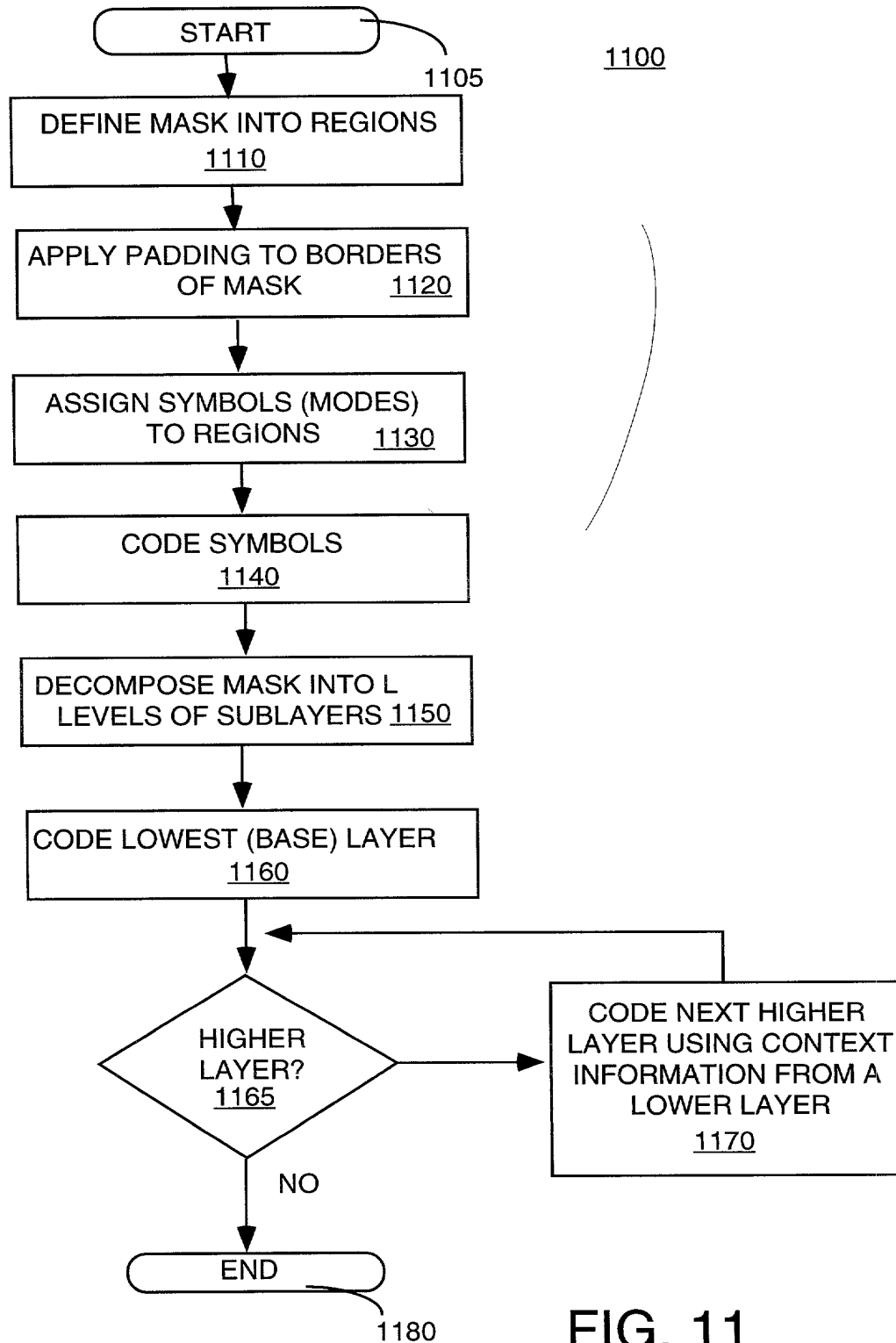


FIG. 11

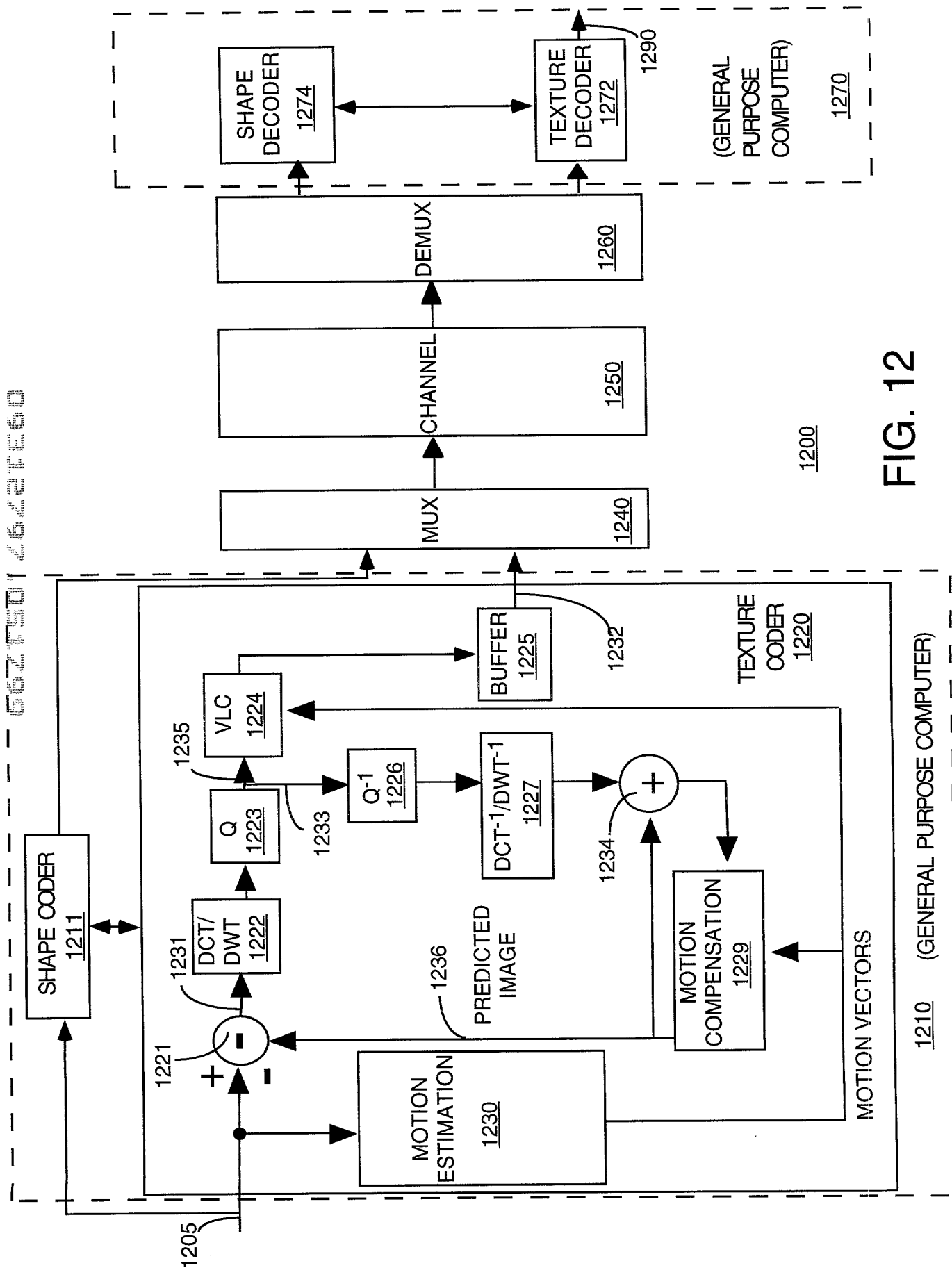
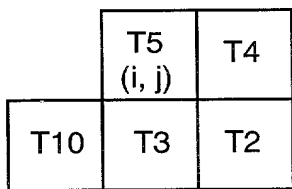


FIG. 12

1400

LOWER LAYER



1410

HALF HIGHER LAYER

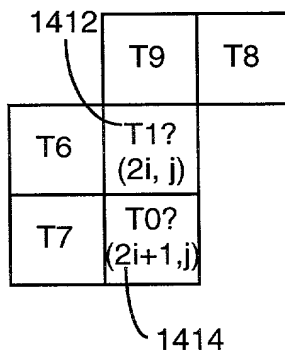
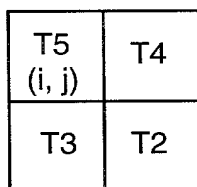


FIG. 14

1500

LOWER LAYER



1510

HALF HIGHER LAYER

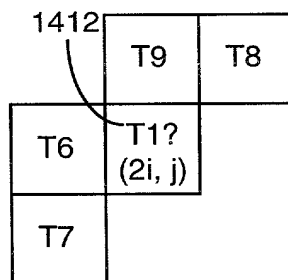
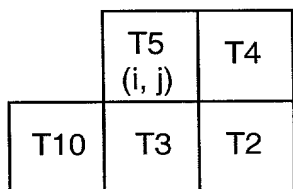


FIG. 15

1600

LOWER LAYER



1412

1610

HALF HIGHER LAYER

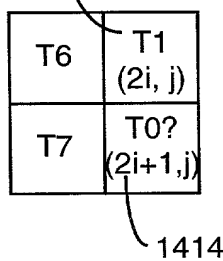
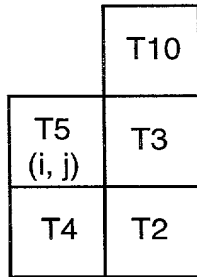


FIG. 16

1700 HALF HIGHER LAYER



1710 CURRENT LAYER

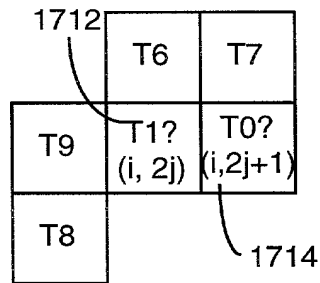
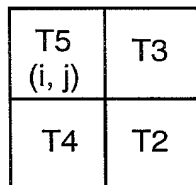


FIG. 17

1800 HALF HIGHER LAYER



1810 CURRENT LAYER

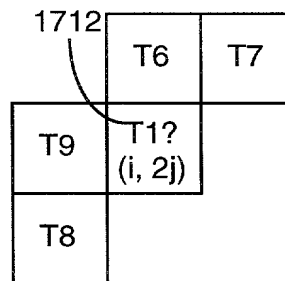
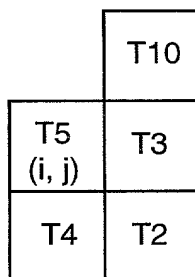


FIG. 18

1900 HALF HIGHER LAYER



1910 CURRENT LAYER

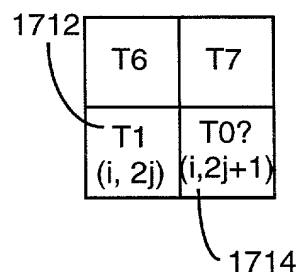


FIG. 19

9/11

2000
LOWER LAYER

T3 (i, j)	T2
T1	T0

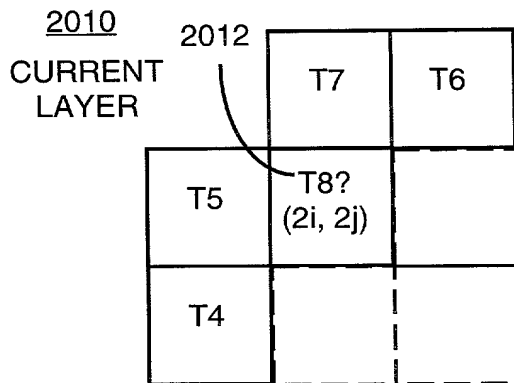


FIG. 20

2100
LOWER LAYER

T3 (i, j)	T2
T1	T0

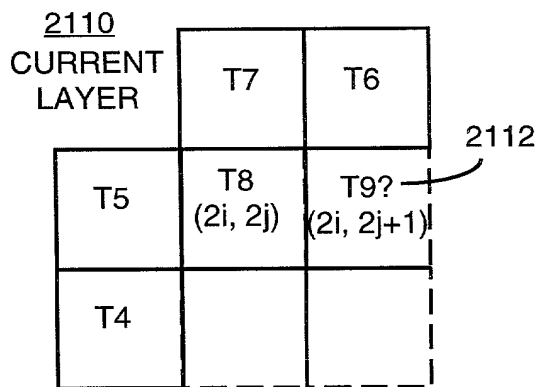


FIG. 21

2200
LOWER LAYER

T3 (i, j)	T2
T1	T0

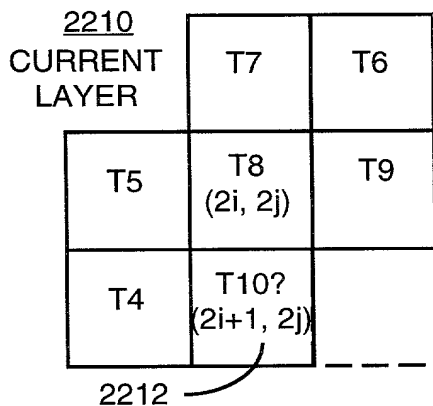


FIG. 22

2300
LOWER LAYER

T3 (i, j)	T2
T1	T0

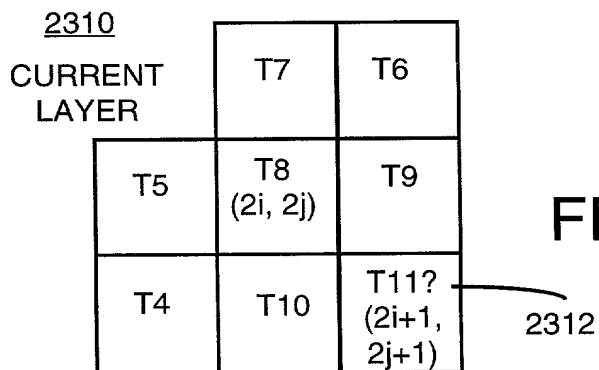


FIG. 23

662750 6227E60

2400
LOWER LAYER

T3 (i, j)	T2
T1	T0

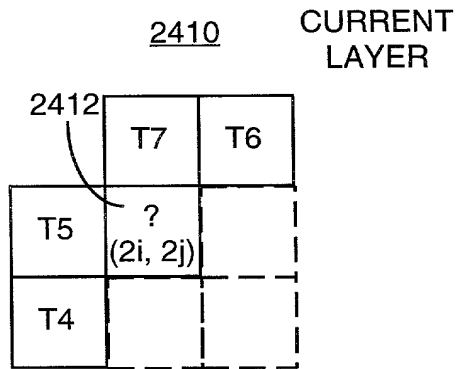


FIG. 24

2500
LOWER LAYER

T3 (i, j)	T2
T1	T0

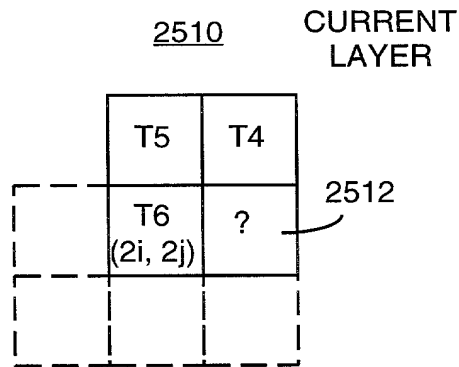


FIG. 25

2600
LOWER LAYER

T3 (i, j)	T2
T1	T0

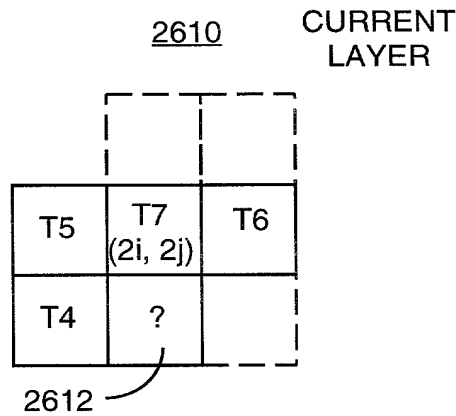


FIG. 26

2700
LOWER LAYER

T3 (i, j)	T2
T1	T0

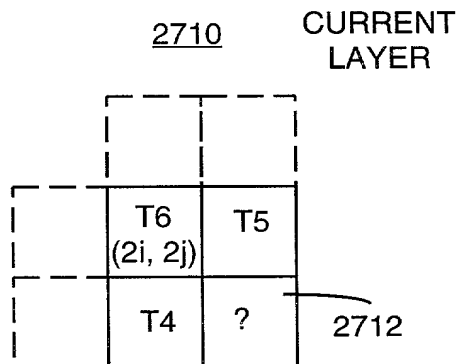


FIG. 27

2800
LOWER LAYER

T3 (i, j)	T2
T1	T0

2810 CURRENT LAYER

	T7	T6
T5	2812 ?	(2i, 2j)
T4		

FIG. 28

2900
LOWER LAYER

T3 (i, j)	T2
T1	T0

2910 CURRENT LAYER

	T5	T4
	T6	2912 ?
	(2i, 2j)	

FIG. 29

3000
LOWER LAYER

T3 (i, j)	T1
T2	T0

3010 CURRENT LAYER

T5	T6	
	(2i, 2j)	
T4	3012 ?	

FIG. 30

3100
LOWER LAYER

T3 (i, j)	T2
T1	T0

3110 CURRENT LAYER

	T6	T5
	(2i, 2j)	
	T4	3112 ?

FIG. 31

COMBINED DECLARATION AND POWER OF ATTORNEY

As a below-named inventor, I hereby declare that:

My residence, post office address, and citizenship are as stated below next to my name.

I believe I am the original, first, and sole inventor (if only one name is listed below) or an original, first, and joint inventor (if multiple names are listed below) of the subject matter which is claimed and for which a patent is sought on the invention entitled **METHOD AND APPARATUS FOR GENERIC SCALABLE SHAPE CODING**, the specification of which is being filed under the above-identified Attorney Docket Number.

I hereby state that I have reviewed and understand the contents of the above-identified specification, including the claims, as amended by any amendment referred to above.

I acknowledge the duty to disclose information which is material to the examination of this application in accordance with Title 37, Code of Federal Regulations, § 1.56(a).

PRIORITY CLAIM

I hereby claim foreign priority benefits under Title 35, United States Code, § 119 of any foreign application(s) for patent or inventor's certificate listed below and have also identified below any foreign application for patent or inventor's certificate having a filing date before that of the application on which priority is claimed.

_____ (Number)	_____ (Country)	_____ (Day/Month/Year Filed)	____ Yes ____ No (Priority Claimed)
_____ (Number)	_____ (Country)	_____ (Day/Month/Year Filed)	____ Yes ____ No (Priority Claimed)

I hereby claim the benefit under Title 35, United States Code § 120 of any United States application(s) listed below and, insofar as the subject matter of each of the claims of this application is not disclosed in the prior United States application in the manner provided by the first paragraph of Title 35, United States Code, § 112, I acknowledge the duty to disclose material information as defined in Title 37, Code of Federal Regulations, § 1.56(a) which occurred between the filing date of the prior application and the national or PCT international filing date of this application.

_____ (Application Serial No.)	_____ (Filing Date)	_____ (Status) (patented, pending, abandoned)
_____ (Application Serial No.)	_____ (Filing Date)	_____ (Status) (patented, pending, abandoned)

I hereby claim the benefit under Title 35, United States Code, § 119(e) of any United States provisional application(s) listed below:

PROVISIONAL APPLICATION NUMBER

60/103,012

60/090,815

FILING DATE

5 October 1998

26 June 1998

POWER OF ATTORNEY

As a named inventor, I hereby appoint the following attorneys jointly and each of them severally, with full power of substitution, delegation, and revocation, to prosecute this application, to make alterations and amendments therein, to receive the patent, and to transact all business in the Patent and Trademark Office connected therewith:

William J. Burke, Reg. No. 29,138
 John V. Silverio, Reg. No. 34,014
 Abhik A. Huq, Reg. No. 40,656

I hereby direct that all correspondence and telephone calls in connection with this application be addressed to:

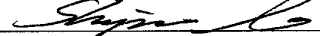
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 Fax.(609) 734-2673

DECLARATION

I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code, and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

SIGNATURES

Full name of **first inventor**: Shipeng Li

Inventor's signature: 

Date: May 13, 1999 Country of Citizenship: **P.R. China**

Residence and Post Office Address: 303 Berkshire Drive, Princeton, NJ 08540